

Design, Implementation and Deployment of an MLOps pipeline for AI-powered Smart Cameras and Cloud Enviroment over AWS

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Dedicata a i miei Genitori

Abstract

The centralized Cloud Computing model has been demolished by recent technology and conceptual advances, which have shifted Cloud services to developing infrastructures such as Edge, which are closer to end-users. Because smart devices are becoming more widespread, powerful, and affordable, conventional Cloud computing programming approaches are being challenged by the recent expansion of the IoT phenomena. As a result, services must be located near such devices. In this sense, we seek to deliver a new cloud computing service based on infrastructure and application deployment and migration methodologies between Cloud and Edge. In this thesis, we will propose a Machine Learning Object Detection Model for recognizing gestures from International Sign Language shown on a webcam-equipped device to facilitate communication between a speech-impaired individual and someone unfamiliar with Sign Language. Depending on the infrastructure available, we developed this model in two distinct contexts to confront different needs and requirements. Indeed, we were able to develop an Edge and a Cloud Implementation using a variety of tools and services for the Cloud system, ranging from Amazon Web Services to the libraries and dependencies required for the function's proper execution. The findings show how different systems respond to different demands in terms of latency, cost, and simplicity of deployment; it will be obvious later in this work that the Edge System offers certain advantages, such as faster execution time, but requires a more sophisticated configuration. The Cloud System, on the other hand, is slightly slower but has higher scalability and does not require an extra board for processing. Finally, we make the source code and the development process available to the public to encourage anybody interested in implementing their project to do so, resulting in the creation of many more useful services for the consumers. It will be continuously updated in the future with new devices and functionality.

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Chapter 1 Introduction

1.1 Overall problem

We're surrounded by social networking sites, online content, and other online services in the cloud computing era, a precursor to edge computing, giving us access to data from anywhere at any time. Next-generation applications centered on machine-tomachine interaction, such as the internet of things (IoT), machine learning, and artificial intelligence (AI), will shift the focus to "edge computing", which is the anti-cloud in many aspects. Edge computing refers to bringing the power of cloud computing closer to the customer's premises at the network edge, allowing them to compute, analyze, and make real-time choices. Transporting closer to the network edge is intended to improve network speed, improve service dependability, and lower the cost of moving data computation to distant servers, hence reducing bandwidth and latency difficulties. Over the last two decades, the wireless sector has grown and new technology has been used, resulting in a rapid movement from on-premise data centers to cloud servers. With the growing number of Industrial Internet of Things (IoT) applications and devices, computing in data centers or cloud servers may not be the most efficient option. Cloud computing necessitates a lot of bandwidth to transmit data from the customer's location to the cloud and back, which adds to the delay. Due to the tight latency requirements for IoT applications and devices that demand real-time calculation, computing capabilities must be located at the edge—closer to the data generating source. Because of the numerous benefits in terms of latency, bandwidth, and security, edge computing has seen increasing acceptance, with rises in IoT applications and devices. Edge computing, although ideal for IoT, may benefit any application that would benefit from reduced latency and more efficient network use by reducing the computational burden on the network carrying the data back and forth.

1.2 The approach and goals of the thesis

Since the computing capacity of smart devices has substantially expanded, our research will concentrate on transitioning cloud-centric settings to edge-based configurations whenever possible. In particular, build and deploy a machine learning model for AI-powered Smart Cameras connected through AWS IoT, bringing what

was previously only feasible in a cloud environment closer to the edge to exploit the benefits. Furthermore, because this transformation has potential consequences in multiple areas, including project integration and delivery, we'll make sure to get to a point where our system is simple to adapt and expand to new devices brought to the group. In addition, because all of the logic is stored in one place and uploaded to hosts that can be accessed nearly infinitely, it is straightforward to update the code and grow the implementation in the cloud. In an edge environment, however, the issue becomes more difficult since every new device must be given all of the logic it requires, which can be time-consuming. However, we can build a repository where all the functions are stored using services like CloudFormation and CodeCommit, and we can generate the entire group in a matter of seconds, ensuring a CI/CD approach to the entire system. To be more specific, in our instance, we wish to build and create a device that will assist and include all persons with speech impairments in society by allowing them to cooperate and communicate with anybody using these new technologies. In the beginning, it will be critical to concentrate on the model's building; we must, in fact, train the model using a collection of pictures that allows us to detect sign language effectively. Because extremely identical motions are frequently present, a fine differentiation is necessary for an accurate prediction. We need to make our infrastructure smart in order for this model to work properly. If we consider the world of business or even your own house, it is clear that replicating this approach across several devices would be quite difficult. As a result, you may design and deploy infrastructure from CloudOps to EdgeOps, as we'll see later using Amazon Web Service. This will enable us to detect and analyze the strengths and limitations in both scenarios, giving us a clear picture of the best option for you depending on your requirements. As a result, our goal was to make the entire project useful and broad, so that our infrastructure could be used for comparison purposes with object detection as the key focus. The analysis, design, and implementation carried out at the code level to allow the changing of these parameters will be detailed in the next chapters.

1.3 Structure of the thesis

Various components of the project achieved in this thesis work, and therefore the phases of design, execution, and testing, will be examined in the following chapters, but also in terms of the technologies and services that characterize the project, to make the potential of this approach in all of its numerous aspects understandable to the greatest possible audience. In Chapter 2, we'll look at cloud and edge designs, their main features, and implementations, as well as the services that were required. In Chapter 3, we'll explain our project's Use Case, which, while only one of many conceivable applications, we keep in mind. We describe why we made this decision and outline the steps we took to get to where we are now while working on this project. The Cloud-Centric System is explored in further depth in Chapter 4, which demonstrates how to use deployable machine learning to produce predictions and store them in a database. Chapter 5, on the other hand, adapts what we built in the previous chapter to make it deployable in an Edge Environment, as well as all of the extra processes and needs required to have a fully functional smart device capable of

deploying a machine learning model. Instead, in Chapter 6, we'll compare the two solutions, examining both in terms of execution time (from the start of capturing frames to the upload of predictions to the database) and service costs. Finally, in the final chapter, the findings and concluding considerations concerning this thesis project, as well as probable future advancements, will be discussed.

Chapter 2

Model Deployment at the Edge

In the following chapters, we'll create a Cloud-centric architecture using a Smart Camera to capture frames and a Machine Learning model to make a database prediction. The next stage will be to convert all of this design into an Edge-Based architecture, which has its own set of benefits and drawbacks. To make our project more accessible to anyone that wants to implement it, we have used a lot of different services that also helped us a great deal during the Design and Implementation phases. In particular, we used several tools from the Amazon Web Services console, AWS is one if not the most used platform offering services for cloud computing, storage, training, and much more. There are more realities out there and they all work very well with competitive costs, but for clarity and simplicity, we decided to stick with Amazon's services for all our needs. Amazon Web Services, Inc. (AWS) is a subsidiary of Amazon providing on-demand cloud computing platforms and APIs to individuals, companies, and governments, on a metered pay-as-you-go basis. These cloud computing web services provide a variety of basic abstract technical infrastructure and distributed computing building blocks and tools. AWS's virtual computers emulate most of the attributes of a real computer, including hardware central processing units (CPUs) and graphics processing units (GPUs) for processing; local/RAM; hard-disk/SSD storage; a choice of operating systems; networking; and pre-loaded application software such as web servers, databases, and customer relationship management (CRM). The AWS technology is implemented at server farms throughout the world and maintained by the Amazon subsidiary. Fees are based on a combination of usage (known as a "Pay-as-you-go" model), hardware, operating system, software, or networking features chosen by the subscriber required availability, redundancy, security, and service options. These are paid services, but AWS provides a free tier you can use to experiment and even implement without the fear of "wasting" money. More on the costs of these services will be studied later in this thesis showing some use cases. Following here we will give a brief description of all the services used for the sake of fluidity later in the paper.

2.1 Architectures

2.1.1 Cloud-Centric

Cloud computing is the on-demand availability of computer system resources, especially data storage (cloud storage) and computing power, without direct active management by the user. Large clouds often have functions distributed over multiple locations, each location being a data center. Cloud computing relies on sharing of resources to achieve coherence and economies of scale, typically using a "pay-as-you-go" model which can help in reducing capital expenses but may also lead to unexpected operating expenses for unaware users. This means that much more bandwidth will be used and that some latency of transfer on the prediction might be present.



Figure 2.1. Cloud-Centric Architecture

2.1.2 Edge-Based

Edge computing is a distributed computing paradigm that brings computation and data storage closer to the sources of data. This is expected to improve response times and save bandwidth. The idea behind our interest in designing an implementation in an Edge System comes from the fact that to perform machine learning tasks the data exchanged is typically relatively big in size. This could generate bandwidth and delay problems when the system will perform real-time execution and invocation of the ML model. The solution to this could be loading the model on a device that will acquire all the information needed by the model, manipulate them locally as to send only the data necessary for the execution of the function which would obviously be smaller.



Figure 2.2. Edge-Centric Architecture

2.2 Cloud-based ML Technologies

2.2.1 Machine Learning

The practice of assisting software in performing a task without explicit programming or rules is known as machine learning. A programmer specifies rules for the computer to follow in traditional computer programming. However, ML necessitates a different mindset. Real-world ML is more concerned with data analysis than with coding. Programmers provide a set of examples, and the computer uses the data to learn patterns. Machine learning can be thought of as "data programming." Machine learning is a field that is constantly evolving. As a result, there are a few things to think about when working with machine learning methodologies or analyzing the impact of machine learning processes. Tasks are generally classified into broad categories in machine learning. These classifications are based on how learning is received and how the system is given feedback on the learning. Supervised learning and unsupervised learning are two of the most widely used machine learning methods. Unsupervised learning, which provides the algorithm with no labeled data in order to allow it to find structure within its input data, and supervised learning, which trains algorithms based on example input and output data that is labeled by humans, are two of the most widely used machine learning methods. Deep learning tries to mimic how the human brain converts light and sound into vision and hearing. A deep learning architecture is inspired by biological neural networks and consists of multiple layers in an artificial neural network made up of hardware and GPUs. Deep learning extracts or transforms data features using a cascade of processing unit layers. One layer's output is used as the input for the next layer. Deep learning, the most widely used and developed machine learning algorithm, absorbs the most data and has been shown to outperform humans in various cognitive tasks. Deep learning has become the approach with the most potential in the artificial intelligence area

as a result of these characteristics. Deep learning algorithms have made substantial advances in computer vision and speech recognition. A neural network is a patternrecognition model that can be trained. It has layers that include input and output layers, as well as at least one concealed layer. Each layer's neurons learn increasingly abstract data representations. For example, we can see neurons identifying lines, shapes, and textures in this visual representation. These representations (or learned characteristics) allow the data to be classified. In our case, machine learning will allow us to create a model that recognizes the Sign Language gesture shown to our device's camera, which brings us to our use of IoT. Combining services from AWS in the Machine Learning (ML) and Internet of Things (IoT) space, training a custom computer vision model, and running it at the edge has become easier than ever. In computer vision, image classification tells you what type of objects are in the image. Object detection, in addition to defining objects, also tells you where the objects are by producing bounding boxes that mark the location of each object being detected.

2.2.2 Amazon Web Services

2.2.3 Amazon SageMaker

Amazon SageMaker is a fully managed service that provides every developer and data scientist with the ability to build, train, and deploy machine learning (ML) models quickly. SageMaker removes the heavy lifting from each step of the machine learning process to make it easier to develop high-quality models. Amazon SageMaker helps data scientists and developers to prepare data and build, train, and deploy machine learning models quickly by bringing together purpose-built capabilities. These capabilities allow you to build highly accurate models that improve over time without all the undifferentiated heavy lifting of managing ML environments and infrastructure. As for any model training, you need lots of data. SageMaker lets you connect and load your data from sources such as Amazon S3 so that you can use this data to train your model. Models learn complex and subtle patterns to let you map inputs to predicted outputs. You can retrieve an entire data set for training. Once your model is deployed, you can retrieve individual features to make low latency predictions, such as predicting in real-time. Next, great models can be used in different situations if they are trained on a balanced set of features and data. You can use SageMaker Clarify to identify potential bias in your training data. This will help you ensure your model is trained across a range of genres, leading to more accurate predictions. You can also use SageMaker Clarify to inspect individual predictions to understand how each feature plays a role in the prediction. This allows you to check that the model isn't overly reliant on features that are underrepresented in the data. One of the great things about machine learning is that models can improve over time, not just based on new data as it becomes available, but also by incorporating the learnings from tools like SageMaker Clarify and SageMaker Debugger to systematically identify sources of error or slowness and remove them from your model. With this approach, you can condense hundreds of thousands of hours of real-world experience into just a few retraining iterations, so your models can improve quickly. And since you want to continually improve the model by rebuilding it regularly, you can take advantage of Amazon SageMaker Pipelines,

which provides continuous integration. This decreases the time between model improvements and delivers better models more quickly. Amazon SageMaker provides tools that every developer is familiar with, visual editors, debuggers, profilers, and CI/CD, all wrapped into the Amazon SageMaker Studio integrated development environment for machine learning.

2.2.4 Amazon SageMaker Ground Truth

In 2018, Amazon Sagemaker Ground Truth was launched to fully manage data labeling services for generating high-quality ground truth datasets to be trained into machine learning models. Ground Truth can integrate Amazon Mechanical Turk(the crowdsourcing platform) or internal data labeling team or external 3rd party vendors to get the labeling job done. Workflows can be customized or made use of built-in. This labeled dataset output from Ground Truth can be used to train their models or as a training dataset for an Amazon SageMaker model. Sagemaker Ground truth offers a wide range of services in image, audio, video, and text having features such as removal of distortion in images, automatic 3D cuboid snapping, and auto-segment tools to reduce the labeling time. Auto Labelling is possible using semi-supervised learning, where it learns to label the data. Varied pricing for each labeled object (image/video frame, audio recording, a section of the text, etc.) whether it's labeled automatically by Ground Truth or by a human labeler. If you use a vendor or Mechanical Turk to provide labels, you pay an additional cost per labeled object. If you use your employees for labeling, there is no additional cost per labeled object. The workforce type can be public or private mode.

2.2.5 Apache MXNet in AWS

Model Server for Apache MXNet (MMS) is an open-source component that is designed to simplify the task of deploying deep learning models for inference at scale. Deploying models for inference is not a trivial task. It requires collecting the various model artifacts, setting up a serving stack, initializing and configuring the deep learning framework, exposing an endpoint, emitting real-time metrics, and running custom pre-process and post-process code, to mention just a few of the engineering tasks. While each task might not be overly complex, the overall effort involved in deploying models is significant enough to make the deployment process slow and cumbersome. With MMS, AWS contributes an open-source engineering toolset for Apache MXNet that drastically simplifies the process of deploying deep learning models. The key features that we can achieve through the use of MXNet are different, as tooling to package and export all model artifacts into a single "model archive" file that encapsulates everything required for serving an MXNet model or the ability to customize every step in the inference execution pipeline, from model initialization, through pre-processing and inference, up to post-processing the model's output.

2.2.6 OpenCV

OpenCV (Open Source Computer Vision Library) is a library of programming functions mainly aimed at real-time computer vision. Originally developed by Intel, it was later supported by Willow Garage then Itseez. The library is cross-platform and free for use under the open-source Apache 2 License. Starting with 2011, OpenCV features GPU acceleration for real-time operations. OpenCV is a great tool for image processing and performing computer vision tasks. It is an open-source library that can be used to perform tasks like face detection, objection tracking, landmark detection, and much more. The library is equipped with hundreds of useful functions and algorithms, which are all freely available to us. Some of these functions are really common and are used in almost every computer vision task. Whereas many of the functions are still unexplored and haven't received much attention yet. OpenCV's application areas include:

- 2D and 3D feature toolkits
- Facial recognition system
- Gesture recognition
- Human-computer interaction (HCI)
- Mobile robotics
- Object detection
- Segmentation and recognition
- Motion tracking
- Augmented reality

2.3 Cloud-based Storage Services

2.3.1 Amazon S3

It is probably the most commonly used, go-to storage service for AWS users given the features like extremely high availability, security, and simple connection to other AWS Services. AWS S3 can be used by people with all kinds of use cases like mobile/web applications, big data, machine learning, and many more. An object consists of data, key (assigned name), and metadata. A bucket is used to store objects. When data is added to a bucket, Amazon S3 creates a unique version ID and allocates it to the object.

2.3.2 Amazon DynamoDB

Amazon DynamoDB is a fully managed, serverless, key-value NoSQL database designed to run high-performance applications at any scale. DynamoDB offers built-in security, continuous backups, automated multi-region replication, in-memory caching, and data export tools. With DynamoDB, there are no servers to provision, patch, or manage, and no software to install, maintain or operate. DynamoDB automatically scales tables to adjust for capacity and maintains performance with zero administration. Availability and fault tolerance are built-in, eliminating the need to architect your applications for these capabilities. It provides capacity modes for each table: on-demand and provisioned. For workloads that are less predictable for which you are unsure that you will have high utilization, on-demand capacity mode takes care of managing capacity for you, and you only pay for what you consume. Tables using provisioned capacity mode require you to set read and write capacity. Provisioned capacity mode is more cost-effective when you're confident you'll have decent utilization of the provisioned capacity you specify. For tables using the on-demand capacity mode, DynamoDB instantly accommodates your workloads as they ramp up or down to any previously reached traffic level. If a workload's traffic level hits a new peak, DynamoDB adapts rapidly to accommodate the workload. You can use on-demand capacity mode for both new and existing tables, and you can continue using the existing DynamoDB APIs without changing the code.

2.4 Cloud-based Access Control and Accounting

2.4.1 AWS Identity and Access Management (IAM)

Amazon Web Services (AWS) cloud provides a secure virtual platform where users can deploy their applications. Compared to an on-premises environment, AWS security provides a high level of data protection at a lower cost to its users. There are many types of security services, but Identity and Access Management (IAM) is one the most widely used. AWS IAM enables you to securely control access to AWS services and resources for your users. Using IAM, you can create and manage AWS users and groups, and use permissions to allow and deny their access to AWS resources.

2.4.2 Amazon CloudWatch

Amazon CloudWatch is a component of Amazon Web Services that provides monitoring for AWS resources and the customer applications running on the Amazon infrastructure.

CloudWatch enables real-time monitoring of AWS resources such as Amazon Elastic Compute Cloud (EC2) instances, Amazon Elastic Block Store (EBS) volumes, Elastic Load Balancing, and Amazon DynamoDB tables. The application automatically collects and provides metrics for CPU utilization, latency, and request count. Users can also stipulate additional metrics to be monitored, such as memory usage, transaction volumes, or error rates. Users can access CloudWatch functions through an application programming interface (API), command-line tools, one of the AWS software development kits, or the AWS Management Console. The CloudWatch interface provides current statistics that users can view in graph format. Users can set notification alarms to be sent when something being monitored surpasses a specified threshold. The app can also detect and shut down unused or underused EC2 instances.

2.5 Compute

2.5.1 AWS Lambda

AWS Lambda is a serverless compute service that lets you run your code without worrying about provisioning or managing any server. You can run your application or back-end service using AWS Lambda with zero administration. Just upload your code on Lambda, and it will run your code, even scale the infrastructure with high availability. The code which you run on AWS Lambda is called a lambda function. Currently, it supports many languages but what we will use will be Python. AWS Lambda easily scales the infrastructure without any additional configuration. It reduces the operational work involved and it offers multiple options like AWS S3, CloudWatch, DynamoDB, API Gateway, Kinesis, CodeCommit, and many more to trigger an event. An important feature is you don't need to invest upfront. You pay only for the memory used by the lambda function and minimal cost on the number of requests hence cost-efficient and also AWS Lambda is secure, it uses AWS IAM to define all the roles and security policies.

2.5.2 Amazon Elastic Container Registry(ECR)

Amazon ECR is a fully managed container registry offering high-performance hosting, so you can reliably deploy application images and artifacts anywhere. Amazon ECR stores your container images and artifacts in Amazon S3. This means that your data is available when needed and protected against failures, errors, and threats. Amazon ECR can also automatically replicate your data to multiple AWS Regions for your high availability applications. Amazon ECR stores both the containers you create and any container software you buy through AWS Marketplace. AWS Marketplace for Containers offers verified container software for high-performance computing, security, and developer tools, as well as SaaS products that manage, analyze, and protect container applications. In our case, ECR is used to contain the function and model to implement the Cloud Environment System since AWS Lambda does not allow files of size bigger than 250MB while the libraries needed by the model are way heavier than that.

2.5.3 Docker

Docker is an open platform for developing, shipping, and running applications. Docker enables you to separate your applications from your infrastructure so you can deliver software quickly. With Docker, you can manage your infrastructure in the same ways you manage your applications. By taking advantage of Docker's methodologies for shipping, testing, and deploying code quickly, you can significantly reduce the delay between writing code and running it in production. Docker simplifies and accelerates your workflow while giving developers the freedom to innovate with their choice of tools, application stacks, and deployment environments for each project. Docker is the de facto standard to build and share containerized apps from desktops to the cloud. In the scope of our project, Docker is crucial since we need to create a container image of our function in order for it to be deployed in the AWS Lambda environment. An image is a read-only template with instructions for creating a Docker container. Often, an image is based on another image, with some additional customization. You might create your own images or you might only use those created by others and published in a registry. To build your own image, you create a Dockerfile with a simple syntax for defining the steps needed to create the image and run it. Each instruction in a Dockerfile creates a layer in the image. When you change the Dockerfile and rebuild the image, only those layers which have changed are rebuilt. This is part of what makes images so lightweight, small, and fast when compared to other virtualization technologies.

2.6 Edge technologies

2.6.1 Internet of Tings

The Internet of Things (IoT) describes the network of physical objects—"things"—that are embedded with sensors, software, and other technologies for the purpose of connecting and exchanging data with other devices and systems over the internet. These devices range from ordinary household objects to sophisticated industrial tools; kitchen appliances, thermostats, weather stations but also cars, and the greatly discussed industry 4.0. Over the past few years, IoT has become one of the most important technologies of the 21st century. Now that we can connect everyday objects to the internet via embedded devices, seamless communication is possible between people, processes, and things. By means of low-cost computing, the cloud, big data, analytics, and mobile technologies, physical things can share and collect data with minimal human intervention. In this hyperconnected world, digital systems can record, monitor, and adjust each interaction between connected things. While the idea of IoT has been in existence for a long time, a collection of recent advances in a number of different technologies has made it practical.

- Access to low-cost, low-power sensor technology. Affordable and reliable sensors are making IoT technology possible for more manufacturers.
- **Connectivity**. A host of network protocols for the internet has made it easy to connect sensors to the cloud and other "things" for efficient data transfer.
- Cloud computing platforms. The increase in the availability of cloud platforms enables both businesses and consumers to access the infrastructure they need to scale up without actually having to manage it all.
- Machine learning and analytics. With advances in machine learning and analytics, along with access to varied and vast amounts of data stored in the cloud, businesses can gather insights faster and more easily. The emergence of

these allied technologies continues to push the boundaries of IoT and the data produced by IoT also feeds these technologies.

• Conversational artificial intelligence (AI). Advances in neural networks have brought natural-language processing (NLP) to IoT devices (such as digital personal assistants Alexa, Cortana, and Siri) and made them appealing, affordable, and viable for home use.

When something is connected to the internet, that means that it can send information or receive information, or both. This ability to send and/or receive information makes things "smart." To be smart, a thing doesn't need to have super storage or a supercomputer inside of it - it just needs access to it. In the Internet of Things, all the things that are being connected to the internet can be put into three categories: 1. Collecting and Sending Information

Imagine a smart farm that uses sensors to collect information useful to the farmer. Sensors could be temperature sensors, motion sensors, moisture sensors, air quality sensors, or many more. These sensors, along with a connection, allow us to automatically collect information from the environment which, in turn, allows us to make more intelligent decisions. This could give relevant information to who it may concern so that he may act accordingly to the information received. 2. Receiving and Acting on Information

It's not a surprise that we can send commands to devices to trigger their functions; we can send a signal to a printer to receive our pdf, or with the help of a remote controller we can change the channel without getting up from our couch. So what's so incredible about this? The real power of the Internet of Things arises when things can do both of the above. Things that collect information and send it, but also receive information and act on it. The real power of the Internet of Things arises when things can do both of the above. Things that collect information and send it, but also receive information and act on it. 3. Doing Both: The Goal of an IoT System Let's quickly go back to the farming example. The sensors can collect information about the soil moisture to tell the farmer how much to water the crops, but you don't need the farmer. Instead, the irrigation system can automatically turn on as needed, based on how much moisture is in the soil. Or maybe if the irrigation system receives information about the weather from its internet connection, it can also know when it's going to rain and decide not to water the crops today because they'll be watered by the rain anyways. What if all this information about the soil moisture, how much the irrigation system is watering the crops, and how well the crops grow can be collected and sent to supercomputers that run amazing algorithms that can make sense of all this information? The applications are limitless and can be easily implemented without great costs thanks to the platform available on the web. Our application of IoT is to use smart camera devices that will record their surroundings to collect and send images displaying gestures from the ISL alphabet so that they can be predicted and stored. Running computer vision algorithms at the edge unlocks many industry use cases that have low or limited internet connectivity.

2.6.2 AWS IoT Greengrass

AWS IoT Greengrass is an open-source edge runtime and cloud service for building, deploying, and managing device software. AWS IoT Greengrass provides pre-built components so you can easily extend edge device functionality without writing code. AWS IoT Greengrass components enable you to add features and quickly connect to AWS services or third-party applications at the edge. IoT devices can vary in size, ranging from smaller microcontroller-based devices to large appliances. AWS IoT Greengrass Core devices, AWS IoT Device SDK-enabled devices, and FreeRTOS devices can be configured to communicate with one another.

If the AWS IoT Greengrass Core device loses connectivity to the cloud, connected devices can continue to communicate with each other over the local network. You can deploy, run, and manage Docker containers on AWS IoT Greengrass devices. Your Docker images can be stored in Docker container registries, such as Amazon Elastic Container Registry (Amazon ECR), Docker Hub, and then used on AWS Lambda for the device's logic. Greengrass includes support for AWS Lambda. You can run AWS Lambda functions on the device to respond quickly to local events, interact with local resources, and process data to minimize the cost of transmitting data to the cloud. AWS Lambda functions deployed on an AWS IoT Greengrass Core can access local resources that are attached to the device. This allows you to use serial ports, peripherals such as the board camera, or the local file system to quickly access and process local data as you will see later. AWS IoT Greengrass ML Inference is a feature of AWS IoT Greengrass that makes it easy to perform machine learning inference locally on AWS IoT Greengrass devices using models that are built and trained in the cloud. This means you won't incur data transfer costs or increased latency for applications that use machine learning inference.

$2.7 \quad \text{CI/CD}$

2.7.1 GitHub Repository

Through all the exposition of our work, we will often reference several scripts, files, or configurations that we used in different parts of the project. These are part of our approach on the implementation, we will make them all available to the public so as to ease the reproduction or possible changes to better suit your need. Our GitHub repository containing all the files separated in folders for each "phase" is published at the following link:

https://github.com/alessandromigliore/TesiObjectDetection

2.7.2 AWS CodeCommit

AWS CodeCommit is a secure, highly scalable, managed source control service that hosts private Git repositories. It makes it easy for teams to securely collaborate on code with contributions encrypted in transit and at rest. CodeCommit eliminates the need for you to manage your own source control system or worry about scaling its infrastructure. You can use CodeCommit to store anything from code to binaries. It supports the standard functionality of Git, so it works seamlessly with your existing Git-based tools. AWS CodeCommit stores your repositories in Amazon S3 and Amazon DynamoDB. Your encrypted data is redundantly stored across multiple facilities. This architecture increases the availability and durability of your repository data. You can transfer your files to and from AWS CodeCommit using HTTPS or SSH, as you prefer. Your repositories are also automatically encrypted at rest through AWS Key Management Service (AWS KMS) using customer-specific keys.

2.7.3 AWS CodePipeline

AWS CodePipeline is a continuous delivery service that helps you automate your build and deploy stages, which leads to faster product delivery and early mitigation of issues. AWS CodePipeline sits in a CI/CD setup, it lets you integrate your source code from multiple sources, such as GitHub, Amazon S3, AWS CodeCommit, etc, monitor it continuously for any code change, and generate builds when any change is detected. Just like any continuous delivery service, AWS CodePipeline helps teams deliver features and updates rapidly.

2.7.4 AWS CloudFormation

AWS CloudFormation lets you model, provision, and manage AWS and third-party resources by treating infrastructure as code. With CloudFormation you can automate, test, and deploy infrastructure templates with continuous integration and delivery (CI/CD) automation. It gives you an easy way to model a collection of related AWS and third-party resources, provision them quickly and consistently, and manage them throughout their lifecycles, by treating infrastructure as code. A CloudFormation template describes your desired resources and their dependencies so you can launch and configure them together as a stack. You can use a template to create, update, and delete an entire stack as a single unit, as often as you need to, instead of managing resources individually. AWS also provides a visual designer, that can be used if you don't have familiarity with YAML files, to have a clear view of how all the different services are connected and interact with each other.

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Chapter 3

Use Case

3.1 Background

We find that in today's society, inclusion is one of the most important topics discussed daily, people live, work and generally feel better when they are not abandoned, when society thinks about their needs and does everything in its power to help them. With the aid of Machine Learning and IoT we think we can help, even if just a little, people to live in a world where they feel they could belong. For this reason, we decided to create an easily implementable project to convince public and private businesses to adopt our product in favor of the inclusion of speech-impaired people since, unfortunately, the vast majority of people don't know Sign Language as they do not deem it necessary. In this paper we will show every necessary step in order to implement completely the project; remember that this is just an application and is not by any means at its final stage and can be modified to respond to other needs. We would be happy if we have helped in any way.

3.2 International Sign Language

Sign languages are natural languages that have the same linguistic properties as spoken languages. They have evolved over years in the different Deaf Communities across the world and Europe. Despite widespread opinions, there is not one single universal sign language in the world or even in Europe. Just as spoken languages, sign languages vary greatly between countries and ethnic groups. Some countries have more than one sign language or the dialect. Countries that have the same spoken language do not necessarily have the same signed language (see for example Germany and Austria). In recent years Deaf people have been traveling extensively, taking part in international events, which increased the need for a "lingua franca", much like English is widely used today. Experience has shown that it is difficult to teach IS to anyone not knowing at least one or more national sign languages. For this reason, we find useful a way to help deaf people to be understood in everyday life in a society where not many non-deaf people have any knowledge of Sign Language. As a simple example, nowadays workers that are required to interface with a lot of people, like hotel or airport staff, need to have a good knowledge of the English Language as it is the one most used in a commercial environment but could be

caught off guard if a speech-impaired person tries to communicate with them. It is important to say that with our project we do not want to force in any way a global spread of a single Sign Language because it is "better this way". We find it beautiful and crucial to have differences in all the SLs since are part of the country's roots and traditions. Hopefully, our desire to just help is clear.



Figure 3.1. International Sign Language

3.3 Model Training

With these premises, it is important to create and appropriately train a model to reach our goal in the best way possible. In fact, the project also wants to highlight the differences and analogies of the implementation of the same Machine Learning Object Detection Model in two different environments, namely in Edge and Cloud systems. As we mentioned already, our Object Detection (OD) model will be used to recognize the gestures shown to our smart camera from a set of gestures coming from the International Sign Language (ISL) alphabet. So the first step is to train an OD model since it is the main part of both implementations. Once we have our deployable model we can use it in a Cloud Environment to infer the gesture from an image or to create our Internet Of Things (IoT) Device that does all it needs to perform the prediction.

3.3.1 Data Preparation

The first, and also one of the most crucial, in the creation of any ML model is the collection, preparation, and selection of the data that will be used for the training of the model. The quality of the data chosen will influence greatly the performance of the model, the time necessary for its training, and the reliability of the prediction. As we said several times now, our model is an Object Detection Model that will analyze images to recognize gestures from the ISL alphabet, so in order to train a model that is capable of doing this, we will have to prepare a proper dataset. To create our images that will form the set we used OpenCV through a Python script to record a video using our device's webcam and from the said video we retrieve all the frames as different images. Keep in mind that this is just a way as any other to retrieve a group of images with the same characteristics, you can use the method you

prefer like just capturing the images one by one and separating them by category. Obviously, by using this method, we will have several junk frames that cannot be used cause they, are blurred, bring no value to the model cause it is identical to other frames, or are just transition frames where no gesture is shown. We have to get rid of them by performing a selection of the frames that will better carry out the final job. We repeated this process for each gesture we wanted to have in the project and ended up having 40 different images for the 30 different signals we agreed upon. A good practice to use when recording the videos is to have the final images slightly different from the previous one so that the model will work better even if you are not holding your hand up in the exact same way you did while training; we addressed this by slowly rotating and moving our hands during the recording to show the hand in different angles. Now that we have completed this part, we can upload all the selected images in a folder of our S3 bucket so that we can create a Labeling Manifest that will be needed in the next part by GroundTruth to retrieve the images for labeling.

3.3.2 Labeling with AWS GroundTruth

With all the images in our Bucket, all we need to do to create our Labeling Manifest is to execute the corresponding script specifying the location of the frames in S3. This way a new JSON file containing the URI to the images will be created and can later be uploaded in our Bucket and retrieved by the GroundTruth console. The JSON manifest will look somewhat like this.

```
{"source-ref": "s3://signlanguagebucket/frames/frameA (1).jpg"}
{"source-ref": "s3://signlanguagebucket/frames/frameA (10).jpg"}
{"source-ref": "s3://signlanguagebucket/frames/frameA (12).jpg"}
{"source-ref": "s3://signlanguagebucket/frames/frameA (12).jpg"}
...
...
{"source-ref": "s3://signlanguagebucket/frames/frameZ (5).jpg"}
{"source-ref": "s3://signlanguagebucket/frames/frameZ (6).jpg"}
{"source-ref": "s3://signlanguagebucket/frames/frameZ (7).jpg"}
{"source-ref": "s3://signlanguagebucket/frames/frameZ (8).jpg"}
{"source-ref": "s3://signlanguagebucket/frames/frameZ (9).jpg"}
```

Now we can start with the labeling job. The labeling is a crucial phase of our model training because we will be saying to our model that a definite image corresponds to a definite gesture so that our algorithm will learn to discern and classify different signs. AWS GroundTruth comes to our help during this phase by retrieving the images referenced in the manifest and providing us with a tool that allows us to draw a bounding box around the hand making the gesture; let's see how to set this task. From the AWS SageMaker Console access the GroundTruth section and select Labeling Jobs, here you can specify an Input Dataset Location that is the path to your manifest, and an Output Dataset Location that indicates where you want your final output to be stored. Then you have to specify the type of task you want to label; there are several with different characteristics depending on what you wish to accomplish. In our case, we will select Bounding Box as the Task Type since we want to classify and annotate the position of the gesture.



Figure 3.2. GroundTruth Task Types

The next step is to select the workforce that will label your images. There are different options available, each with its costs, pros, and cons. You can select an external workforce that will label your data for you, this will considerably speed up your job but it is obviously paid and need you to give clear instruction to the workers if you want a job well done. Alternatively, you can select a private workforce (which can consist even of you and your friends) and work on your data yourself. Keep in mind though that labeling is a time-consuming job, and depending on the number of images that need to be labeled can become obnoxious and can take some time. With this said, you can add the classes of your images and add some good and bad examples in case you use an external workforce; when the labeling job is completed, you will have an output file containing the image name, the box position, the corresponding class and other metadata used later in the training. A good practice with this kind of labeling is to draw the box as close as possible to the object and not to include parts of the object that are overlapping or that cannot be seen, even though you think you can interpolate the whole shape. Also, you might want to check the labeling job from the console to see if some misclassifications are present.

3.3.3 Training with AWS SageMaker

Process SageMaker Ground Truth labeling job outputs for training

The output of the SageMaker Ground Truth bounding box labeling job is in a format called augmented manifest file. Using an augmented file allows us to gain numerous benefits from our training input. For example, there is no need for a format conversion if we use Sagemaker Ground truth to generate data labels, or instead of the traditional approach of providing paths to the input images separately from its labels, augmented manifest file already combines both into one entry for each input image, reducing complexity in algorithm code for matching each image with labels. Also after splitting our dataset into train/validation instead of re-uploading our file images into the respective folders in the S3. Once you upload your image files to S3, you never need to move them again, you can just place pointers to these images in your augmented manifest file for training and validation. A last important note about the augmented file is that with its use the training input images are loaded onto the training instance in Pipe mode, which means the input data is streamed directly to the training algorithm while it is running. This results in faster training performance and less disk resource utilization. In our thesis project although our augmented file is supported by Amazon Sagemaker it may be appropriate to perform some small processing:

- Join outputs from multiple jobs: To be able to iterate on Ground Truth jobs, we created several smaller labeling jobs for our dataset instead of a single large job containing the full dataset.
- Discard any bad labels from visual inspection: this step is optional, you may manually review the labeled bounding boxes on the Ground Truth console and mark the image IDs that didn't pass a quality bar.
- Inject the correct class labels: This step is useful in case the labeler has not been asked, during the labeling work done on Ground Truth, to choose the right class when drawing the delimiting boxes. This means that in our manifest there is only one class_id: 0 because you only specified one class of objects when you submitted the labeling job.
- Split dataset between train and validation: As mentioned above, Amazon Sagemaker requires you to split the dataset during training, a train, and a validation dataset. The training set consists of all frames and all records used to train the model, while validation is used to validate that the model can accurately make predictions on previously unseen data, and is also used to compare accuracy between different training jobs during hyperparameter tuning.
- Data Augmentation (optional): This simple technique allows us to reach a higher accuracy quickly and cheaply, through two python scripts in fact we

create a copy for each frame rotated on the axis of x and y of 90 degrees. We found that even simple data augmentation like this can make a significant difference in accuracy.

Amazon SageMaker Object Detection using the augmented manifest file format

Now that we have finished with all the required setups, we can start our training jobs. Using boto3 SDK, by Amazon Sagemaker, we can define input train and validation.



Figure 3.3. Output JSON File

Inserting in S3 URI the link to our bucket contain the input images, and attribute name for the bounding box annotations. Next, set the hyperparameters. You can find documentation for all the supported hyperparameters in the Amazon SageMaker documentation. In this case, we recommend leaving the recommended parameters, knowing that our algorithm This algorithm uses a base_network, which is typically a VGG or a ResNet, and changing only the number of classes, according to your choice.

```
{"base_network": "resnet-50",
"use_pretrained_model": "1",
"num_classes": "30",
"mini_batch_size": "10",
"epochs": "10",
"learning_rate": "0.001",
"lr_scheduler_step": "10,20",
"lr_scheduler_factor": "0.25",
"optimizer": "sgd",
"momentum": "0.9",
```

```
"weight_decay": "0.0005",
"overlap_threshold": "0.5",
"nms_threshold": "0.45",
"num_training_samples": "5400",
"image_shape": "512",
"_tuning_objective_metric": "",
"_kvstore": "device",
"kv_store": "device",
"_num_kv_servers": "auto",
"label width": "150",
"freeze_layer_pattern": "",
"nms_topk": "400",
"early_stopping": "False",
"early_stopping_min_epochs": "10",
"early_stopping_patience": "5",
"early_stopping_tolerance": "0.0",
"_begin_epoch": "0"}
```

Now we just have to create our own Sagemaker training jobs. To carry out this last part you need special permissions from the Amazon platform, you can get the necessary resources by contacting the support and indicating our development region and the notebook instance that requires the resource. Once the necessary resources have been obtained we create the SageMaker training job.

| mazon SageMaker Training jobs | | | | | | | | | | |
|--------------------------------|---|----------|------------------------|---|--------------------------------|-------------|----------|--|--|--|
| Train | ing jobs | | | C | C Actions Create training job | | | | | |
| Q : | iearch training jobs | | | | | < 1 > | < 1 > @ | | | |
| | Name | ∇ | Creation time | • | Duration | Status | ∇ | | | |
| 0 | SignLanguageDetection-2021-11-26-15-34-02 | | Nov 26, 2021 15:34 UTC | | 14 minutes | ⊘ Completed | | | | |
| 0 | objectDetection-2021-10-03-09-41-10 | | Oct 03, 2021 09:41 UTC | | 6 minutes | ⊘ Completed | | | | |
| 0 | xgboost-2021-09-18-15-21-32-621 | ! | Sep 18, 2021 15:21 UTC | | 3 minutes | ⊘ Completed | | | | |

Figure 3.4. SageMaker Training Jobs

Once the training job completes, move on to the next notebook to convert the trained model to a deployable format and run local inference.

3.3.4 Creating Deployable Model

Now we have completed the training of our model, but in order to check its functioning, we need to adjust our model artifact so that it can be deployed.

The trained model parameters along with its network definition are stored in a tar.gz file in the output path for the training job. We need to download and unzip it to a

local disk in order to work on it. Inside the tar file you will find 3 files stored that together form our trained model :

- model_algo_1-symbol.json: neural network definition
- hyperparams.json: hyperparameters
- model_algo_1-0000.params: trained weights for the neural network

The model output produced by the built-in object detection model leaves the loss layer in place and does not include a non-max suppression (NMS) layer. To make it ready for inference on our machine, we need to remove the loss layer and add the NMS layer. We will be using a script from this GitHub repo: https://github.com/zhreshold/mxnet-ssd Make sure to execute the script just as we do in the provided ipynb Notebook because the parameters passed in the function must correspond to the hyperparameters you used in the training phase or it will not work. This will create two files that will be uploaded in our S3 Bucket.

- deploy_model_algo_1-0000.params
- deploy_model_algo_1-symbol.json

Now, if we want to, we can perform a test inference selecting an image, deploying the model, and checking if the classification is coherent with our training. You can do it by following the mentioned notebook that will guide you in the creation of a PDF file with the predictions of the selected images of a batch. This is our result.









Figure 3.5. Report Visualization

Now we are ready for the real implementation of the model; we will start with the Edge Environment where we will create a GreenGrass device to perform the prediction.
Chapter 4

Cloud-Based Services

4.1 Introduction

Our main interest in creating a Cloud Environment implementation is the fact that you don't need any personal infrastructure since you will be using services already present on the internet. In fact, here obviously we don't have any external device that can perform the prediction so all the separate images need to be sent to the function in charge of loading the model, which will later provide the upload of the recognized gesture on our Database.



Figure 4.1. Cloud Architecture

The system is composed of a local device, external to the environment, that is in charge of capturing the images. Those images will be first uploaded to an S3 Bucket and then retrieved by our Lambda that will perform the prediction and will finally create an item in our DynamoDB. Let's see all these steps one by one.

4.2 Images collection and upload

Since we don't have a smart device with a camera, we need a computer external to our system that with a webcam captures the images so that they can be sent for prediction to our function. The script used to achieve this task will be pretty similar to the one used in the edge system; the main difference is that the images retrieved from the video will be uploaded since we need a place where to store them for later. To do so we will use the boto3 library to connect to our bucket in the specified region.

```
1 import cv2
2 import time
3 import logging
4 import json
5 import os
6 import time
7 import boto3
8 from botocore.client import Config
9 from botocore.exceptions import ClientError
10 import numpy as np
11 import urllib
12
13
14 def main():
  video_fname = '#PATH FOLDER/VIDEO NAME'
15
16
   camera_id = 0
17
   cap = cv2.VideoCapture(camera_id)
18
19
   # Define the codec and create VideoWriter object. For mac mp4v or
20
      avil is the best option.
   # You can also use: 0x00000021 if this codec doesn't work for you
21
   fourcc = cv2.VideoWriter_fourcc(*'MJPG')
22
23
   # Create a video writer, specify the codec as well as the image
24
      widge and height.
   # cap.get(3) is the width, and cap.get(4) is the height of the
25
      camera in cap.
   out = cv2.VideoWriter(video_fname, fourcc, 5.0, (int(cap.get(3)),
26
      int(cap.get(4))))
27
   start_time = time.time()
28
29
   while( int(time.time() - start_time) < 10 ):</pre>
30
    ret, frame = cap.read()
31
32
    if ret==True:
33
     out.write(frame)
34
35
     #if cv2.waitKey(1) \& 0xFF == ord('q'):
36
     # print("\nstop signal received.")
37
     # break
38
39
40
    else:
        break
41
42
```

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```
43
   # When everything done, release the capture
44
   cap.release()
45
   out.release()
46
   cv2.destroyAllWindows()
47
48
49
   # Opens the Video file
50
   cap2= cv2.VideoCapture('#PATH FOLDER /VIDEO NAME')
51
   i=0
52
   while(cap2.isOpened()):
53
        ret, frame = cap2.read()
54
        if ret == False:
55
            break
56
57
        if i % 10 == 0:
58
         cv2.imwrite('#PATH FOLDER/frame'+str(i)+'.jpg',frame)
59
         client = boto3.client('s3', region_name='eu-west-1')
60
61
         client.upload_file('#PATH FOLDER/frame'+str(i)+'.jpg',
                                                                     '#BUCKET
        ,'images/frame'+str(i)+'.jpg')
62
        i+=1
63
   cap2.release()
64
   cv2.destroyAllWindows()
65
66
67 main()
```

Listing 4.1. Video Recording Function

Each image uploaded in the bucket will later trigger the Lambda function that is the heart of our Cloud implementation.

4.3 The Lambda Function

The main part of the Cloud Environment is without a doubt the creation of Lambda function that by itself needs to receive the images, load the model, perform the prediction, create an item and finally upload that item to the DynamoDB. All of this obviously requires a relevant amount of space that the "classical" configuration of AWS Lambda does not support; in fact, Lambda Functions can only be created from zip files if the total size between the main file plus any additional layer does not exceed 250MBs of space. This amount is way too strict since we need libraries like OpenCV, MXNET, and the model itself that are more than 100MBs each. The way around this limitation is the fact that Amazon allows the creation of Lambdas with container images with a maximum size of 10GBs which is more than enough. This means that we need a container image holding all our files and libraries, let's see how to do that.

4.3.1 Lambda with Container Image

Using container images for your lambdas you can easily build and deploy larger workloads that rely on sizable dependencies, such as machine learning or data-intensive workloads. Just like functions packaged as ZIP archives, functions deployed as container images benefit from the same operational simplicity, automatic scaling, high availability, and native integration with many services. Amazon provides base images for all the supported Lambda runtimes (Python, Node.js, Java, .NET, Go, Ruby) so that you can easily add your code and dependencies. So we will use the Python base image as a start for our container where model and libraries will be added. The base image for Python can be found at the following link:

https://docs.aws.amazon.com/lambda/latest/dg/python-image.html Before creating the Dockerfile, we need the main Python script that does what we described earlier; it will retrieve the item uploaded to the S3 bucket specified, will create an image from the raw data retrieved, it then calls the script in charge of loading the model and the prediction, from the prediction result it creates an item that will be put inside our database. Notice that to access your bucket and database from a script you need to provide your Amazon credentials that were removed from this snippet for security. In case you want to reproduce this script functioning replace it with your credentials.

```
1 #
2 # Copyright 2010-2017 Amazon.com, Inc. or its affiliates. All Rights
      Reserved.
3
4
5 # Lambda entry point
6 from model_loader import MLModel
7 import logging
8 import os
9 import time
10 import json
11 import boto3
12 from botocore.client import Config
13 from botocore.exceptions import ClientError
14 import os
15 import numpy as np
16 import urllib
17 import cv2
18
19 dynamodb = boto3.resource("dynamodb", region_name="eu-west-1")
20 tableName = "#DATABASENAME'
21 predicted_gesture = "none"
22 seven_days_as_seconds = 604800
23
24 s3_signature ={
<sup>25</sup> 'v4':'s3v4',
26 'v2':'s3'
27 }
28
29 ML_MODEL_BASE_PATH = 'model/'
30 ML_MODEL_PREFIX = 'deploy_model_algo_1'
31 ML_MODEL_PATH = os.path.join(ML_MODEL_BASE_PATH, ML_MODEL_PREFIX)
32 # Creating a greengrass core sdk client
33
34 #client=boto3.client('iot-data', endpoint_url='a3gtyikpk9vqi1-ats.iot
      .eu-west-1.amazonaws.com')
35
36 model = None
37
38 # Load the model at startup
```

```
39 def initialize(param_path=ML_MODEL_PATH):
40
   global model
   model = MLModel(param_path)
41
42
43
44 def lambda_handler(event, context):
   bucket_name = event['Records'][0]['s3']['bucket']['name']
45
   key = event['Records'][0]['s3']['object']['key']
46
47
   generated_signed_url = create_presigned_url(bucket_name, key,
48
    seven_days_as_seconds, s3_signature['v4'])
49
    print(generated_signed_url)
50
    image_complete = url_to_image(generated_signed_url)
51
52
   start = int(round(time.time() * 1000))
53
    prediction = model.predict_from_file(image_complete)
54
    end = int(round(time.time() * 1000))
55
56
57
   response = {
58
    'prediction': prediction,
     'timestamp': time.time()
59
   }
60
61
       if prediction[0][0] == 0:
62
       predicted_gesture = "A"
63
       elif prediction[0][0] == 1:
64
       predicted_gesture = "B"
65
       elif prediction[0][0] == 2:
66
       predicted_gesture = "C"
67
68
       . . .
69
       . . .
70
       . . .
71
       elif prediction[0][0] == 25:
72
       predicted_gesture = "Hello"
       elif prediction[0][0] == 26:
73
       predicted_gesture = "NO"
74
       elif prediction[0][0] == 27:
75
       predicted_gesture = "YES"
76
       elif prediction[0][0] == 28:
77
       predicted_gesture = "ILoveYou"
78
       elif prediction[0][0] == 29:
79
       predicted_gesture = "ThankYou"
80
81
    global tableName
82
    table = dynamodb.Table(tableName)
83
    table.put_item(
84
    Ttem={
85
      "Gesture ID": str(time.time()),
86
      "prediction": predicted_gesture,
87
     "filepath": key
88
    }
89
   )
90
91
92
   return response
93
94
95 def url_to_image(URL):
```

```
resp = urllib.request.urlopen(URL)
96
       image = np.asarray(bytearray(resp.read()), dtype="uint8")
97
       image = cv2.imdecode(image, cv2.IMREAD_COLOR)
98
99
       return image
100
102 def create_presigned_url(bucket_name, bucket_key, expiration=3600,
       signature_version=s3_signature['v4']):
       s3_client = boto3.client('s3',
104
                             aws_access_key_id=#YOUR ACCESS KEY ID",
                             aws_secret_access_key=#YOUR SECRET ACCESS
106
      KEY.
                             config=Config(signature_version=
      signature_version),
                             region_name='eu-west-1'
108
109
110
       trv:
           response = s3_client.generate_presigned_url('get_object',
      Params={'Bucket': bucket_name, 'Key': bucket_key}, ExpiresIn=
      expiration)
           print(s3_client.list_buckets()['Owner'])
           for key in s3_client.list_objects(Bucket=bucket_name,Prefix=
113
      bucket_key)['Contents']:
               print(key['Key'])
114
       except ClientError as e:
115
           logging.error(e)
116
           return None
117
    # The response contains the presigned URL
118
119
       return response
120
121
122 # If this path exists then this code is running on the greengrass
      core and has the ML resources it needs to initialize.
123 if os.path.exists(ML_MODEL_BASE_PATH):
       initialize()
124
125 else:
   logging.info('{} does not exist and we cannot initialize this lambda
126
        function.'.format(ML_MODEL_BASE_PATH))
```

Listing 4.2. Container Image Main File

Once our main function file is completed, we can change the example Dockerfile to fit our needs. As you can see, we are using the public lambda Python 3.8 image offered by Amazon Web Services so that we have the basic libraries and configurations already prepared. First, we load both main.py and model_loader.py that we need for the prediction, then we copy the model artifact in a new folder that we called model, we install libraries and dependencies and finally, we set the CMD to your handler.

```
1 FROM public.ecr.aws/lambda/python:3.8
2
3 # Copy function code
4 COPY main.py ${LAMBDA_TASK_ROOT}
5
6 COPY model_loader.py ${LAMBDA_TASK_ROOT}
7
```

```
8 RUN mkdir model
9
10 COPY deploy_model_algo_1-symbol.json ${LAMBDA_TASK_ROOT}/model
11
12 COPY deploy_model_algo_1-0000.params ${LAMBDA_TASK_ROOT}/model
13
14 COPY hyperparams.json ${LAMBDA_TASK_ROOT}/model
15
16 # Install the function's dependencies using file requirements.txt
17 # from your project folder.
18
19 COPY requirements.txt
20 RUN pip3 install -r requirements.txt --target "${LAMBDA_TASK_ROOT}"
21
_{22} RUN yum -y install tar gzip zlib freetype-devel \backslash
      gcc \
23
      ghostscript \
24
      lcms2-devel \
25
26
      libffi-devel ∖
27
      libimagequant-devel \
28
      libjpeg-devel \
      libraqm-devel \
29
      libtiff-devel \
30
      libwebp-devel \
31
      make \
32
      openjpeg2-devel \
33
      rh-python36 \
34
      rh-python36-python-virtualenv \
35
      sudo \
36
      tcl-devel \
37
      tk-devel \
38
39
      tkinter \
      which \
40
41
      xorg-x11-server-Xvfb \
42
      zlib-devel ∖
      && yum clean all
43
44
45 RUN yum -y install libgomp
46
  RUN yum -y install libquadmath
47
48
49 RUN yum -y install mesa-libGL
50
  # Set the CMD to your handler (could also be done as a parameter
51
      override outside of the Dockerfile)
52 CMD [ "main.lambda_handler" ]
```

Listing 4.3. Dockerfile

Before building the container image, make sure your function folder configuration looks like this to ensure the building will go through fine and to have a perfectly working container since this is a time-consuming process, and re-building many times cause something went wrong can be annoying.

| — myFunction | #Folder of the Docker Image |
|-----------------------|--|
| │ │ | #Dockerfile for the image build |
| │ | #Main python file of our Lambda function |
| │ | <pre>#Python script for loading the model</pre> |
| │ | <pre>#Text file with all dependencies to install</pre> |
| deploy_model_algo_1-0 | 000.params #trained weights for the neural network |
| deploy_model_algo_1-s | ymbol.json #neural network definition |
| │ └─ hyperparams.json | #hyper parameters |
| | |



Now that our Dockerfile is complete we can use the Docker CLI to build the random-letter container image locally. When this step runs without any error we can continue. To upload the container image, I create a new ECR repository in my account and tag the local image to push it to ECR. To help me identify software vulnerabilities in my container images, I enable ECR image scanning.

```
$ aws ecr create-repository --repository-name lambda
--image-scanning-configuration scanOnPush=true
$ docker tag lambda:latest
123412341234.dkr.ecr.eu-west-1.amazonaws.com/lambda:latest
$ aws ecr get-login-password -region eu-west-1 | sudo docker login
--username AWS --password-stdin
123412341234.dkr.ecr.eu-west-1.amazonaws.com
$ docker push 123412341234.dkr.ecr.sa-east-1.amazonaws.com/lambda:latest
```



Figure 4.3. Pushing Container Image in ECR

In order to execute some of these commands, make sure you have correctly configured your AWS CLI. By completing this passage we have successfully uploaded our container image that holds all is necessary to execute our lambda function on Cloud. So we now need to create the function itself. From the Lambda console in AWS select the "Container Image" option and browse to find the right image in your ECR repositories. After I select the repository, I use the latest image I uploaded. When I select the image, the Lambda is translating that to the underlying image digest. You can see the digest of your images locally with the docker images –digests command. In this way, the function is using the same image even if the latest tag is passed to a newer one, and you are protected from unintentional deployments. You can update the image to use in the function code. Updating the function configuration has no impact on the image used, even if the tag was reassigned to another image in the meantime.

| Lambda 📏 Funzioni 📏 Crea funzione | | | |
|---|--|--|--|
| Crea funzione 🗤 | | | |
| Scegli una delle seguenti opzioni per creare la funzione. | | | |
| | | | |
| Crea da zero O Inizia con un semplice esemplo di Hello World. | Usa un piano Crea un'applicazione Lambda dal codice di esempio e dai set di impostazioni di configurazione per i casi di utilizzo comuni. | Immagine del container O Seleziona un'immagine del container da distribuire per la funzione. | Sfoglia il repository dell'app serverless O Distribuisti un'applicazione Lambda di esempio da AWS Serverless Application Repository. |
| Informazioni di base | | | |
| Nome funzione Inserisci un nome che descriva lo scopo della funzione. | | | |
| CloudBlogInfer | | | |
| Utilizza solo lettere, numeri, trattini o caratteri di sottolineatura senza s | azi. | | |
| URI dell'Immagine del container Info La posizione dell'Immagine del container da utilizzare per la funzione. | | | |
| 036027030307.dkr.ecr.eu-west-1.amazonaws.com/lambda@ | lsha256:fce8eb3a1bc893f89b6155eb531a9846909e332ae0633c14 | 44c3c8258b80728a7 | |
| Richiede un URI dell'immagine Amazon ECR valido | | | |
| Sfoglia le immagini | | | |
| Sostituzioni dell'immagine del container | | | |
| Architettura into Scegli l'architettura del set di Istruzioni desiderata per il codice della fun | tone. | | |
| o x86_64 | | | |
| 🔿 arm64 | | | |
| Autorizzazioni Info | | | |
| Come impostazione predefinita, Lambda creerà un ruolo di esecuzione o | on le autorizzazioni a caricare i log in Amazon CloudWatch Logs. Potrai persona | slizzare questo ruolo predefinito ulteriormente durante l'aggiunta di trigger. | |
| Modifica del ruolo di esecuzione predefinito | | | |

Figure 4.4. Creating Lambda with Container Image

Then we can leave all other options untouched. We can now create our Lambda, it will take some time. As an important note if you are using AWS Free Tier during the implementation of this project, uploading a function of this size in an Amazon Elastic Registry (ECR) will rapidly consume all your free use for this service. We noticed that after completing these steps, two days of execution had already exceeded our monthly quota and it started using standard pricing. So, if you want to avoid unwanted expenses we suggest you give an eye out on the billing section every now and then to have a clear vision of the cost management.

4.3.2 Lambda Configuration and Trigger

The function is now ready, but we still need to make some adjustments to make it work properly. First of all, since the function is clearly pretty heavy, we need to grant more memory and a greater timeout interval or it won't be able to complete the work in time. This can be easily achieved by working on the function configuration in the specific section. Now, what we need is a way for the function the be invoked on each frame that has been sent from our local Python script. This is the reason why we decided to upload those images in our bucket so that we could add a trigger to our function to be executed every time a new file with an image extension is loaded in a specific folder of our S3. To create this just click add a new trigger, select S3 for the trigger configuration, and set other parameters like shown in the figure.

| Add trigger |
|--|
| Trigger configuration |
| S3 aws storage |
| Bucket Please select the 53 bucket that serves as the event source. The bucket must be in the same region as the function. |
| 07081996 C |
| Event type Select the events that you want to have trigger the Lambda function. You can optionally set up a prefix or suffix for an event. However, for each bucket, individual events cannot have multiple configurations with overlapping prefixes or suffixes that could match the same object key. |
| All object create events |
| Prefix - optional Enter a single optional prefix to limit the notifications to objects with keys that start with matching characters. |
| images/ |
| Suffix - optional Enter a single optional suffix to limit the notifications to objects with keys that end with matching characters. |
| .jpg |
| Lambda will add the necessary permissions for Amazon S3 to invoke your Lambda function from this trigger. Learn more about the Lambda permissions model. |
| Recursive invocation If your function writes objects to an S3 bucket, ensure that you are using different S3 buckets for input and output. Writing to the same bucket increases the risk of creating a recursive invocation, which can result in increased Lambda usage and increased costs. Learn more |
| I acknowledge that using the same S3 bucket for both input and output is not recommended and that this configuration can cause recursive invocations, increased Lambda usage, and increased costs. |
| Cancel Add |

Figure 4.5. Trigger Configuration

4.4 Conclusions and Tests

Now we have configured all the necessary services to test out the function. We can now upload a JPG image to the created S3 bucket by opening the bucket in the AWS management console and clicking Upload. This will invoke the function on the uploaded frame and its prediction will be uploaded to the DynamoDB specified in the main.py file we pushed in the container image. If this test works correctly, we can even test the function as a whole by executing our local video recording script that should upload images on the bucket for them to be retrieved by the function. The function will then load the model, recognize the gesture and create a new item to put in our DB table. With this, we have completed our Cloud Environment Implementation.

| nac | ges/ | | | | | 🗇 Copia URI |
|---------|--|---|---|---|--|-------------------------------|
| | - | | | | | |
| Dgge | etti Proprietà | | | | | |
| | | | | | | |
| Dgg | jetti (15) | | | | | |
| ili ogg | getti sono le entità fondamentali archivia | te in Amazon S3. Per ottenere un elenco d | tutti gli oggetti nei bucket, puoi utilizzare l'Inventario di Amazon S3 [| Per consentire ad altri utenti di accedere al tuoi oggetti, è i | necessario concedere loro le autorizzazioni esplicitan | nente. Ulteriori informazioni |
| | | | | | | |
| G | Copia URI S3 | Copia URL 🔮 Scarica | Apri 🔄 Elimina Operazioni 🕈 Cres | a cartella | | |
| Q | Trova oggetti per prefisso | | | | | < 1 > (|
| | | | | | | |
| | Nome | ▲ Tipo | ♥ Ultima modifica | ♥ Dimensioni | ♥ Classe di storage | |
| | frame0.jpg | ipg | 06 Dec 2021 11:19:47 AM CET | | 39.2 KB Standard | |
| | frame10.jpg | lpg | 06 Dec 2021 11:19:48 AM CET | | 48.2 KB Standard | |
| | frame100.jpg | ipg | 06 Dec 2021 11:19:53 AM CET | | 46.1 KB Standard | |
| | frame110.jpg | lPg | 06 Dec 2021 11:19:53 AM CET | | 46.3 KB Standard | |
| | frame120.jpg | ipg | 06 Dec 2021 11:19:54 AM CET | | 47.0 KB Standard | |
| | frame130.jpg | ipg | 06 Dec 2021 11:19:55 AM CET | | 46.6 KB Standard | |
| | frame140.jpg | ipg | 06 Dec 2021 11:19:55 AM CET | | 47.0 KB Standard | |
| | frame20.jpg | ipg | 06 Dec 2021 11:19:48 AM CET | | 47.9 KB Standard | |
| | frame30.jpg | ipg | 06 Dec 2021 11:19:49 AM CET | | 48.5 KB Standard | |
| | 🖺 frame40.jpg | ipg | 06 Dec 2021 11:19:49 AM CET | | 48.9 KB Standard | |
| | 🖺 frame50.jpg | ipg | 06 Dec 2021 11:19:50 AM CET | | 49.1 KB Standard | |
| | 🖺 frame60.jpg | ipg | 06 Dec 2021 11:19:51 AM CET | | 48.9 KB Standard | |
| | 🖺 frame70.jpg | ipg | 06 Dec 2021 11:19:51 AM CET | | 48.4 KB Standard | |
| | 🖿 frame80.jpg | lpg | 06 Dec 2021 11:19:52 AM CET | | 47.2 KB Standard | |
| | 🖿 frame90.jpg | jpg | 06 Dec 2021 11:19:52 AM CET | | 46.8 KB Standard | |

(a) Images Loaded to the Bucket

| Voci restituite (28) | | | | C Operazioni 🔻 Crea voce | |
|----------------------|--------------------|----------|--|--------------------------|-----------|
| | | | | | < 1 > 🐵 🖾 |
| | Gesture ID | ∇ | filepath 🔻 | prediction | ∇ |
| | 1635258535.2870028 | | images/frame90.jpg | I Love You | |
| | 1635864834.9030282 | | images/frame60.jpg | I Love You | |
| | 1635855026.175429 | | images/frame20.jpg | NO | |
| | 1635866307.0172663 | | images/frame130.jpg | Thank You | |
| | 1635866301.1642087 | | images/frame120.jpg | Hello | |
| | 1637315789.3692136 | | images/frame100.jpg | ок | |
| | 1635866317.389197 | | images/frame10.jpg | NO | |
| | 1635866300.5409946 | | images/frame0.jpg | NO | |
| | 1635258288.8984847 | | /shared/greengrass/buffer/frame90.jpg | Hello | |
| | 1635870467.6998 | | /shared/greengrass/buffer/frame80.jpg | Thank You | |
| | 1637230426.0475419 | | /shared/greengrass/buffer/frame70.jpg | I Love You | |
| | 1635258522.2904282 | | /shared/greengrass/buffer/frame50.jpg | I Love You | |
| | 1637230614.6049523 | | /shared/greengrass/buffer/frame40.jpg | Hello | |
| | 1637230610.9726896 | | /shared/greengrass/buffer/frame30.jpg | I Love You | |
| | 1635258301.5290308 | | /shared/greengrass/buffer/frame20.jpg | NO | |
| | 1637252656.3158529 | | /shared/greengrass/buffer/frame110.jpg | Hello | |

(b) Prediction stored in the Database

Figure 4.6. Results of Execution of the Cloud Function

Chapter 5

Edge-Based Services

5.1 Introduction

The next step in the building of this project is the actual transposition of the whole system from a Cloud-Centric implementation to the Edge-Based one. Obviously, the most obvious difference between the two, at first sight, is that in Edge we need a smart device that is in charge of the computation closer to the source of data in order to improve response times. In Edge, the device will take care of recording the video, retrieving the frames, invoking the function to receive the prediction based on the frame sent, and finally sending that same prediction to the DynamoDB through the web.

5.2 AWS IoT Greengrass Core software and Greengo Deployment

The first step will be to install and configure the AWS IoT Greengrass Core software on a Linux device, such as a Raspberry Pi, or a Windows device. This device is a Greengrass core device. For the sake of simplicity, we will use a VirtualBox VM on a Windows host that mounts an Ubuntu distribution. The instructions on how to do that can be easily found on Amazon documentation at the following link: https: //docs.aws.amazon.com/greengrass/v1/developerguide/what-is-gg.html If you followed the tutorial at the end you will have installed the GreenGrass Core software and will have provided the AWS credential to execute commands through the AWS CLI. Then we will create the GreenGrass Group and Core Device. there are several ways to do so all analogous; you can use the AWS IoT Core console to use a Graphical Interface to do all the work, you can execute ad hoc commands using AWS CLI, or you use Greengo. Greengo is an open-source project that uses a YAML file to describe a GreenGrass group, device, lambdas, subscription, and resources to have everything created automatically with a simple command. The only problem is that it works on Python2.7 that was recently removed by Amazon for their Lambdas Runtime, so you will need to work around that. In the greengo yaml file, which defines configurations and lambda functions for an IoT Greengrass Group the top portion of the file defines the name of the IoT Greengrass Group and IoT Greengrass Cores:

```
2 Group:
    name: GG_Object_Detection
3
4 Cores:
    - name: GG_Object_Detection_Core
5
      key_path: ./certs
6
      config_path: ./config
7
      SyncShadow: True
8
9
10 Resources:
    - Name: MyObjectDetectionModel
      Id: MyObjectDetectionModel
12
      S3MachineLearningModelResourceData:
13
       DestinationPath: /ml/od/
14
       S3Uri: s3://bucketmigliore/deploy_model.tar.gz
15
```

Listing 5.1. Greengo YAML

Then by executing the corresponding greengo command we create all Greengrass group artifacts in AWS and we place the certificates and config.json for IoT Greengrass Core in ./certs/ and ./config/. In order to perform the deployment to the IoT Core console, we need to move the group certificates and configurations created by greengo to the /greengrass/certs/ and /greengrass/config/ directories on the device. Then we need to download from the web a root CA certificate compatible with the certificates Greengo generated to the /greengrass/certs/ folder. Finally, we can start the IoT Greengrass Core daemon on the edge device so that we are able to navigate back to the greengo folder and deploy. This will deploy the configurations you define in greengo.yaml to the IoT Greengrass Core on the edge device.

| Gru I grup | Sruppi Greengrass (2) gruppi Greengrass organizzaro i dispositivi, le funzioni Lambda e altri componenti locali. Ulteriori informazioni 🗹 | | | | | Elimina | Crea g | ruppo | |
|----------------------|--|-------------|--------------------------------------|----------|--------------|---------|--------|-------|-----|
| Q | Trova i gruppi per nome, ID o ID versio | ne più rece | nte | | | | | < 1 | > @ |
| | Nome | ∇ | ID | ∇ | Creato | | | | |
| | DemoTestGroupNewName | | b44668a6-ffcb-4b99-b518-db2be5e12011 | | 4 giorni fa | | | | |
| | GG_Object_Detection_23 | | fe666791-4d35-4717-b166-212c277e902e | | 19 giorni fa | | | | |
| | GG_Object_Detection_23 | | fe666791-4d35-4717-b166-212c277e902e | | 19 giorni fa | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |

Figure 5.1. GreenGrass Groups

So far we haven't defined any Lambda functions yet in our Greengo configuration, so this deployment just initializes the IoT Greengrass Core and the Machine Learning Resource that takes the deploy_model tar.gz from our S3 Bucket. We will create and add our Lambda Functions from scratch in the next section.

5.3 Creating your inference pipeline in AWS IoT Greengrass Core

We're ready to put it all together now that we've started IoT Greengrass and tested our inference code on the edge device: create a Greengrass Lambda feature that starts recording a video by collecting frames from it, a lambda that executes the inference code inside of Greengrass Core, and a lambda that inserts the value of the prediction into a Database. We'll build the following pipeline to test the Greengrass Lambda IoT functions for inference:



Figure 5.2. Edge Architecture

- When the AWS video/input topic receives a boot message, the Lambda function VideoIngest is called.
- The frame capture code is contained in the Lambda function Videoingest, which starts recording a 10-second video and saves each frame per second in the buffer.
- The AWS IoT topic blog/infer/input will provide the location of the image file on the edge device for the BlogInfer Lambda function to make inference on.
- The object detection inference logic is included in a Lambda function executing in IoT Greengrass Core BlogInfer.
- The IoT dynamo/input topic delivers the Dynamoitem Lambda function the prediction for each frame evaluated in JSON format.

• Finally, the DynamoItem method connects to your DynamoDB and creates a new frame entry with the received message's timestamp and a prediction of the gesture made in the image.

5.4 Lambda Functions

AWS Lambda, as previously mentioned, is a serverless computing service that allows you to run your code without having to worry about deploying or managing any servers. AWS Lambda allows you to execute your application or backend service with zero administration. Simply submit your code to Lambda, and it will execute it as well as grow the infrastructure for high availability. As you can see from the pipeline, we'll be using three lambda functions, each of which will serve a distinct purpose.

5.4.1 VideoIngest

Image acquisition will be of interest to the first Lambda. In actuality, we connect to our smart cameras using Opency, supplying our camera id as an input resource, which is set to 0 by default (this parameter varies according to the USB port of our device). Sending a message to start the Lamba from our IoT Core on the cloud will start recording a video, which will then be split down into frames (for convenience we have chosen as the dividing threshold every 5 frames). Each frame is saved in a buffer and sent to the following lambda via the MQTT protocol. The message's payload includes the filepath for each frame stored in the buffer, as well as the Lambda topic to which the message should be sent.

```
1 # The cloud system does not need to access the device, so the import
      for greengrasssdk is not present
  import greengrasssdk
2
3
  client = greengrasssdk.client('iot-data')
4
5
6
  . . .
7
      if i % 10 == 0:
8
          cv2.imwrite('/buffer/frame'+str(i)+'.jpg',frame)
9
           .....
11
          The Cloud Local Script needs to store the images in a bucket
13
      to trigger the main Lambda Function
14
          client = boto3.client('s3', region_name='eu -west -1')
          client.upload_file('#PATH FOLDER/frame'+str(i)+'.jpg', '#
16
      BUCKET ', 'images/frame '+str(i)+'.jpg')
17
           . . . .
18
19
        msg2 = json.dumps({'filepath':'/shared/greengrass/buffer/frame'
20
      +str(i)+'.jpg'})
        client.publish(topic='blog/infer/input', payload=msg2)
21
        msg = json.dumps('video ingest is sending frame')
```

```
23 msg3 = json.dumps('filepath/shared/greengrass/buffer/frame'+str
(i)+'.jpg')
24 client.publish(topic=OUTPUT_TOPIC, payload= msg + ' ' + msg3)
25 logging.info(msg)
26 i+=1
27
28 cap2.release()
29 cv2.destroyAllWindows()
```

Listing 5.2. VideoIngest Function

The main difference with the cloud counterpart is the fact that the created frames are not uploaded in the S3 bucket, instead they are stored locally and the image local path is provided to the BlogInfer Lambda for the next step.

5.4.2 BlogInfer

The object detection inference algorithm is contained in a lambda function that runs in IoT Greengrass Core BlogInfer. The act of passing live data points through a machine learning algorithm (or "ML model") to compute an output such as a single numerical score is known as machine learning inference. "Operating an ML model" or "bringing an ML model into production" are other terms for this procedure. When a machine learning (ML) model is used in production, it is sometimes referred to as artificial intelligence (AI) since it performs functions akin to human reasoning and analysis. The BlogInfer Lambda function will receive input from the AWS IoT topic blog/infer/input for the location of the picture file on the edge device to conduct inference on. Once the procedure is complete, the prediction output of the BlogInfer Lambda function will be sent via MQTT message to the dynamo/input input topic of the next DynamoItem lambda. The message in JSON format comprises, in addition to the prediction, the timestamp of when the frame was received and the filepath of the same frame, since it is important to know which frame the prediction refers to when saving the message in the database.

```
#
 1
  #
    Copyright 2010-2017 Amazon.com, Inc. or its affiliates. All Rights
2
      Reserved.
3 #
4
5 # Lambda entry point
6 import greengrasssdk
  client = greengrasssdk.client('iot-data')
8
9
10 OUTPUT_TOPIC = 'dynamo/input'
11
12 # Load the model at startup
13 def initialize(param_path=ML_MODEL_PATH):
      global model
14
      model = MLModel(param_path)
15
16
17
  def lambda_handler(event, context):
18
       .....
19
```

```
While the cloud implementation needs a reference to the uploaded
20
      S3 object to download the stream of data and subsequently
      reconstruct the image from it, the Edge System only need the path
      to the image stored locally in order to load it and perform
      prediction.
21
       bucket_name = event['Records'][0]['s3']['bucket']['name']
22
       key = event['Records'][0]['s3']['object']['key']
23
24
       generated_signed_url = create_presigned_url(bucket_name, key,
25
26
       seven_days_as_seconds, s3_signature['v4'])
       print(generated_signed_url)
27
       image_complete = url_to_image(generated_signed_url)
28
29
      .....
30
31
      .....
33
34
      Gets called each time the function gets invoked.
      0.0.0
35
36
       . . .
37
      if 'filepath' not in event:
38
          msg = 'filepath is not in input event. nothing to do.
39
      returning.'
          logging.info(msg)
40
           client.publish(topic=OUTPUT_TOPIC, payload=msg)
41
           return None
42
43
      filepath = event['filepath']
44
45
      if not os.path.exists(filepath):
46
47
          msg = 'filepath does not exist. make sure \'{}\' exists on
      the device'.format(filepath)
48
           logging.info(msg)
           client.publish(topic=OUTPUT_TOPIC, payload=msg)
49
           return None
50
51
52
      . . .
53
      prediction = model.predict_from_file(filepath)
54
      .....
56
57
      Then, BlogInfer creates a message to send via MQTT to the third
58
      and final Lambda DynamoItem that will put a new item in our table
      in DynamoDB.
59
      .....
60
61
      client.publish(topic=OUTPUT_TOPIC, payload=json.dumps(response))
62
      client.publish(topic='blog/infer/output', payload=json.dumps(
63
      response))
```

Listing 5.3. BlogInfer Function

As you can see, the Edge Implementation is somewhat easier with respect to the whole image retrieval since we have no middle step, represented by the upload in S3

in the Cloud. Moreover, since we are already logged to our account in AWS and we are not accessing it from an external device we don't need any authentication and security measures that also often cause unwanted errors.

5.4.3 DynamoItem

DynamoItem via boto3 SDK connects to our Dynamodb, this is because every time an event from the previous Lambda starts the creation of a new item within the Database. This item comprises a key called Gesture ID for each value, which corresponds to the date of the received frame, a second value that provides the frame prediction, and lastly the filepath of the same. Furthermore, the IoT topic dynamo/output will broadcast the DynamoItem Lambda function's prediction output to the AWS IoT message broker in the cloud.

```
import greengrasssdk
 1
2 import boto3
3 import logging
4 import os
5 import time
6 import json
8 dynamodb = boto3.resource("dynamodb", region_name="eu-west-1")
9 tableName = #DYNAMODBNAME
10 client = greengrasssdk.client('iot-data')
11
12 OUTPUT_TOPIC = 'dynamo/output'
13
14
15 def lambda_handler(event, context):
16
    logging.info(event["prediction"])
17
    logging.info(event["filepath"])
18
    global tableName
19
20
    .....
21
22
     global tableName
23
       table = dynamodb.Table(tableName)
24
       table.put_item(
25
        Item={
26
          "Gesture ID": str(time.time()),
27
          "prediction": predicted_gesture,
28
          "filepath": key
29
         }
30
        )
31
32
    .....
33
34
    table = dynamodb.Table(tableName)
35
    table.put_item(
36
37
      Item={
         "Gesture ID": str(time.time()),
38
         "prediction":event["prediction"],
39
         "filepath": event["filepath"]
40
         }
41
    )
42
```

```
44 client.publish(topic=OUTPUT_TOPIC, payload=json.dumps("publish
	prediction on DynamoDB" +':' + event["prediction"] + event["
	filepath"]))
45
```

Listing 5.4. DynamoItem Function

This Lambda is almost identical to the use we make in the previous chapter, the only noticeable difference is the ever-present "greengrasssdk" import necessary for any lambda for Greengrass devices.

| Deployments | Lambdas | Add Lambda |
|---------------|-----------------|------------|
| Subscriptions | | |
| Cores | BlogInfer | 000 |
| Devices | LAMBDA FUNCTION | USING V22 |
| Lambdas | | |
| Resources | Dynamoltem | USING V12 |
| Connectors | LAMBDA FUNCTION | |
| Tags | VideoIngest | ••• |
| Settings | LAMBDA FUNCTION | USING V18 |
| | | |
| | | |

Figure 5.3. Group Lambda Function

5.4.4 Configure Lambda functions

Lambda natively supports a variety of common runtimes, including Python, Node.js, Java, .NET, and others. If you prefer to use any other runtime, such as PHP or Perl, you can use a custom runtime. As we've seen before, we'll use Python 3.8 as our runtime because all of the essential dependencies are already installed. We are now ready to configure your Lambda function for AWS IoT Greengrass. Choose Greengrass, Classic (V1), Groups in the AWS IoT console's navigation pane. Click the previously formed group under Greengrass groups, then choose Lambdas on the group setup page, and then Add Lambda. Look up the name of the Lambda you made in the previous step and copy it. Make the following modifications to the Group-specific Lambda configuration page: Set the Timeout to 60 seconds to ensure that this Lambda function rests for 5 seconds before each call. Select the Lambda lifecycle option, make this function long-lived by allowing read access to the /sys directory and making it run indefinitely. All other fields should be left unchanged, and you should pick Update to save your changes.

 $\mathbf{46}$

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| VideoIngest View function in AWS Lambda | | |
|--|-----------------|-------|
| Version 18 Remove version | | |
| Run as Info | | |
| Use group default (currently: ggc_user/gg | c_group) | |
| Another user ID/group ID | | |
| Containerization Info | | |
| Use group default (currently: Greengrass of the second | :ontainer) | |
| Greengrass container (always) | | |
| No container (always) | | |
| Memory limit | | |
| 900 | МВ | • |
| Timeout | | |
| 1 | Minute | • |
| | | |
| On-demand function | | |
| Make this function long-lived and keep it | running indefir | itely |
| Dood press to Isua divertery | | |
| Read access to /sys directory | | |
| Enable | | |
| \sim | | |
| Input payload data type | | |
| | | |
| U binary | | |

Figure 5.4. Lambda Configuration

5.5 Install machine learning dependencies on the device

If your device has a GPU, check sure you have the appropriate GPU drivers loaded, such as CUDA. You can still execute the inference if your device only has a CPU, but it will be slower. MXNet is used to develop the SageMaker object detection model. You'll need to install the mxnet library on your device to perform inference on the edge. The MXNet version that corresponds to the CUDA driver may be found in the MXNet install manual. For example, on the Ubuntu instance, we installed CUDA 10.1, thus we installed mxnet-cu101.

\$ sudo pip install mxnet-cu101 # on a GPU enabled device with CUDA 10.1

Install mxnet if you're using a CPU-only device.

\$ sudo pip install mxnet # on a CPU only device

Because OpenCV is a huge requirement, we'll also install it on our device:

\$ sudo pip2 install opencv-python

Be extremely cautious throughout these steps, since the dependencies required for inference execution on the device must be installed within the python directory that you need to use for Lambda execution, in our instance, python 3.8, so all packages must be present.

5.6 Local and Machine Learning Resources

5.6.1 Local Resources

To reduce the expense of data transmission to the cloud, you can use AWS Lambda functions on the device to respond fast to local events, interact with local resources, and process data. But, to allow the Lambda Function to access shared folders or even some of the device's peripherals we need to create through AWS Console the corresponding resources. With AWS IoT Greengrass, you can author AWS Lambda functions and configure connectors in the cloud and deploy them to core devices for local execution. On Greengrass cores running Linux, these locally deployed Lambda functions and connectors can access local resources that are physically present on the Greengrass core device. You can access two types of local resources: volume resources and device resources.

- Volume resources
 - Files or directories on the root file system (except under /sys, /dev, or /var)
- Device resources
 - Files or directories on the root file system (except under /sys, /dev, or /var)

This is extremely important for our implementation because for the execution of the first Lambda VideoIngest we need to grant permission to access both a shared folder where the function will save and later retrieve the frames and also the device's camera that will record the video of a person making gestures. Let's start with the shared folder: to allow the function to access any file in the device's root file system we need to declare a Local Resource of Volume type. In this case, we create a shared folder with path source /greengrass/shared/buffer and destination path /buffer as shown in the image.

| Local resource Local resources can be used with Greengrass to make filesystem volumes or physical devices accessible to Greengrass Lambdas while offline. |
|---|
| Resource name buffer Resource type |
| Device |
| Volume |
| Source path |
| /shared/greengrass/buffer |
| Destination path |
| /buffer |
| Group owner file access permission An AWS IoT Greengrass Lambda function process normally runs without an OS Group. However, you can give additional file access permissions to the Lambda function |
| process. |
| No OS group |
| Automatically add OS group permissions of the Linux group that owns the resource |
| Specify another US group to add permission |
| Choose permissions for this Lambda function |
| Read-only access |
| Read and write access |
| |

Figure 5.5. Volume Resource

Then we just need to let it automatically add OS group permissions of the Linux group that owns the resource and attach it to the interested lambda. Instead, to give access to the camera, we need to create a different type of Local Resource. In fact, we need to create a Device Resource specifying the path to the camera in the /dev path. /dev is the location of special or device files. It is a very interesting directory that highlights one important aspect of the Linux filesystem - everything is a file or a directory. Inside this path look for a device that might correspond to your camera (typically video0 or video1) and create a resource with that path. Then attach to the interested Lambda, in our case, it's still the VideoIngest function.

| Local resource Local resources can be used with Greengrass to make filesystem volumes or physical devices accessible to Greengrass Lambdas while offline. | |
|---|--|
| Resource name video0 Resource type Device Volume Device path /dev/video0 Group owner file access permission An AWS IoT Greengrass Lambda function process normally runs without an OS Group. However, you can give additional file access permissions to the Lambda function process. No OS group Automatically add OS group permissions of the Linux group that owns the resource Specify another OS group to add permission | |
| Choose permissions for this Lambda function Read-only access Read and write access | |
| Cancel Update | |

Figure 5.6. Device Resource

5.6.2 Machine Learning Resources

User-defined Lambda functions can access machine learning resources to run local inference on the AWS IoT Greengrass core. A machine learning resource consists of the trained model and other artifacts that are downloaded to the core device. Local Lambda functions can directly engage with machine learning models that are deployed to your Greengrass Core. This is where you specify where to deploy the model locally and how Lambda functions can access it. To allow a Lambda function to access a machine learning resource on the core, you must attach the resource to the Lambda function and define access permissions. The containerization mode of the affiliated (or attached) Lambda function determines how you do this. First, we need to select from our S3 bucket the tar.gz file of our deployable model so that the function has access to the model, then we can specify the path where the model artifacts will be stored. When you need to troubleshoot an ML resource deployment, it's helpful to remember that IoT Greengrass has a containerized architecture and uses filesystem overlay when it deploys resources such as ML model

artifacts. In the example above, even though we configured the ML model artifacts to be extracted to /ml/od/, IoT Greengrass actually downloads it to something like /greengrass/ggc/deployment/mlmodel/<uuid>/. However, to your IoT Greengrass local Lambda function that you declare to use this artifact, the extracted files will appear to your lambda code to be stored in /ml/od due to the filesystem overlay. The OS group and permissions are used by Lambda functions to access downloaded resource artifacts. You must specify an OS group to attach the resource to noncontainerized Lambda functions. If this resource is attached to both containerized and non-containerized Lambda functions, containerized Lambda functions should define read or write permissions that are the same or more restrictive. Notice that, if you followed the greengo example we did earlier, you will already have a machine learning resource created (you can check that in the IoT Core console in the resources tab) identical to the one we just created manually.

| Placini cicarini di 1630. | | |
|--|---|-------------|
| Local Lambda functions can deployed to your Greengras: model locally and how Laml | directly engage with machine learning models that are s Core. This is where you specify where to deploy the oda functions can access it. | |
| Resource name MyObjectDetectionModel Model source Upload a model in S3 | (including models optimized through Deep Learning Compiler) | |
| Use a model trained in Model from S3 | 1 AWS SageMaker | |
| deploy_model.tar.gz | | Change |
| .ocal path | | |
| /ml/od/ | | |
| dentify resource owner an | d set access permissions | |
| The OS group and permissio resource artifacts. You must containerized Lambda funct non-containerized Lambda f read or write permissions th | ns are used by Lambda functions to access downloaded specify an OS group to attach the resource to non- ions. If this resource is attached to both containerized and 'unctions, containerized Lambda functions should define at are the same or more restrictive. | |
| No OS group | | |
| Specify OS group and | permissions | |
| ambda function affiliation | IS | |
| | | |
| BlogInfer | READ AND WRITE ACCESS | Remove Edit |

Figure 5.7. Machine Learning Resource

We just wanted to show you that usually there are different ways to achieve the same objective.

5.7 Subscriptions

A Subscription consists of a source, target, and topic. The source is the originator of the message. The target is the destination of the message. The first step is selecting your source and target. We use subscriptions to make the functions communicate and as a trigger to start the acquisition. We will need to create a connection between each one of the lambda functions and also a link between to IoT Core system to the first lambda to start the whole system. When creating the subscription between two agents, we need to set the topic that must be exactly the one we specified inside the lambda function to make it listen for new messages in that topic. Here you will see the whole picture of the subscriptions for our group.

| Deployments | | Subscriptions | | | Add Subscription | |
|-----------------------------------|----------------------|-------------------|------------------|-------------------|------------------|--|
| Subscriptions Cores Devices | Source | Target | Торіс | | | |
| | DynamoBlogInfer:1 | IoT Cloud | dynamo/output | | | |
| | Lambdas Resources | IoT Cloud | BlogInfer:22 | blog/infer/input | | |
| Connectors Tags Settings | Connectors | BlogInfer:22 | IoT Cloud | blog/infer/output | | |
| | WideoIngest:18 | BlogInfer:22 | blog/infer/input | *** | | |
| | BlogInfer:22 | DynamoBlogInfer:1 | dynamo/input | ••• | | |
| | | WideoIngest:18 | IoT Cloud | video/output | | |
| | | IoT Cloud | VideoIngest:18 | video/input | | |

Figure 5.8. Group Subscriptions

5.8 MQTT Test Client

You can use the AWS IoT MQTT client to better understand the bidirectional communication that occurs between your devices and AWS IoT over the MQTT protocol. The AWS IoT message broker uses topics to route messages from publishing clients to subscribing clients. The forward-slash (/) is used to separate topics into a hierarchy. Devices publish messages on topics to which AWS IoT or your applications can respond. You can use the AWS IoT MQTT client to subscribe to these topics to see the content of these messages or publish messages on these topics to update the device state. In our case the MQTT Test Client also allows us to start our functions. In fact, just by sending an example message to the topic specified in the subscriptions step we can trigger the VideoIngest function that will subsequently start all the others. Also thanks to the messages sent to the IoT Core target we can see the products of execution of each step of the system.

| Subscribe to a topic | Publish to a topic | |
|---|--|--|
| Topic name The topic name identifies the messe | e. The message payload will be published to this topic with a Quality of Service (QoS) of 0. | |
| Q video/input | | × |
| Message payload | | |
| { "message": "Start" } | | |
| Additional configuration Publish | | |
| Subscriptions | video/output | Pause Clear Export Edit |
| video/output 🗢 > dynamo/output 🗢 > | ▼ video/output | December 06, 2021, 16:29:08 (UTC+0100) |
| l blog/infer/output ♡> | "video ingest is sending frame" "filepath/shared/greengrass/buffer/frame100.jpg" | |
| | ▼ video/output | December 06, 2021, 16:29:07 (UTC+0100) |
| | "video ingest is sending frame" "filepath/shared/greengrass/buffer/frame150.jpg" | |
| | ▼ video/output | December 06, 2021, 16:29:07 (UTC+0100) |
| | "video ingest is sending frame" "filepath/shared/greengrass/buffer/frame140.jpg" | |

Figure 5.9. Output of VideoIngest

| Subscribe to a topic | Publish to a topic | |
|---|---|--|
| Topic name The topic name identifies the mes | e. The message payload will be published to this topic with a Quality of Service (QoS) of D. | |
| Q video/input | | × |
| Message payload | | |
| { " <u>message</u> ": "Start" } | | đ |
| Additional configuration Publish | | |
| Subscriptions | blog/infer/output | Pause Clear Export Edit |
| video/output 🛇 | | December 05, 2021, 15:20:42 (UTC+0100) |
| dynamo/output | blog/infer/output | December 06, 2021, 16,25,42 (010-0100) |
| blog/infer/output | <pre>("prediction": "hello", "thestaw": 1538004582.1855572, "fliepath": "/shared/greengrass/buffer/frame100.jpg")</pre> | |
| | ♥ blog/infer/output | December 06, 2021, 16:29:40 (UTC+0100) |
| | { "prediction": "hello", "timestamp": 1638864580.1094688, "filepath": "/shared/greengrass/buffer/frame150.jpg" | |

Figure 5.10. Output of BlogInfer

| Subscribe to a to | pic | Publish to a topic | | |
|---|---------------------|---|-------|--|
| Topic name The topic name identifies | the message. | The message payload will be published to this topic with a Quality of Service (QoS) of 0. | | |
| Q video/input | | | × | |
| Message payload | | | | |
| { "message": "Start" } | | | li di | |
| Additional configu Publish | iration | | | |
| Subscriptions | | dynamo/output | | Pause Clear Export Edit |
| video/output | $\heartsuit \times$ | | | |
| dynamo/output | $^{\diamond}\times$ | ▼ dynamo/output | | December 06, 2021, 16:29:42 (UTC+0100) |
| blog/infer/output | QΧ | "publish prediction on DynamoD0:hello/shared/greengrass/buffer/frame160.jpg" | | |
| | | ▼ dynamo/output | | December 06, 2021, 16:29:40 (UTC+0100) |
| | | "publish prediction on DynamoD8:hello/shared/greengrass/buffer/frame150.jpg" | | |
| | | ▼ dynamo/output | | December 06, 2021, 16:29:38 (UTC+0100) |
| | | | | |

Figure 5.11. Output of DynamoItem

In a naive world, we'd have to construct a group, a core, and all the lambdas, resources, and subscriptions for every device in the network. This is highly timeconsuming and laborious, and it also introduces more potential points of failure where things may go wrong due to human errors or a system bug. Continuous integration is a software development approach in which developers merge new code they've written more often during the development cycle, at least once a day, into the codebase. Each iteration of the build is subjected to automated testing to uncover integration issues early when they are easier to resolve and to avoid difficulties during the release's final merging. Overall, continuous integration speeds up the development process, resulting in higher-quality software and more predictable delivery times. We use Amazon Web Services CodeCommit and CodePipeline to overcome this challenge and to accomplish continuous integration and delivery. Finally, using AWS CloudFormation, we'll develop a Stack that, when run via the mentioned service, will generate all of the elements required for the Edge System.

Chapter 6 Evaluation

6.1 Introduction

Project Evaluation is the process of assessing an ongoing or completed project by gathering data at each stage of the project. The project assessment is carried out to understand the level of progress in a project: Is it progressing according to the planned aims and objectives? How many goals have been achieved? What are the challenges being faced by the team? How is the performance of each team member? And so on. Project Evaluation is carried out at different stages of a project life cycle, starting from the commencement of the project to completion. You can use tools like surveys, to have a complete understanding of your project progress.

- 1. Project Evaluation during Project Commencement
- 2. Preliminary Stage Evaluation
- 3. Project Evaluation during Project Progress
- 4. Post Project Evaluation

In the scope of our project, we decided to conduct our project evaluation taking into consideration the differences of the two implementations, the performance of each, the costs sustained in the creation of the project, some possible case studies, what was good, what went wrong and what could have gone better.

6.2 Edge and Cloud Implementations

In the implementation of the Edge and Cloud environment for our project the differences showed themselves very clearly since, after all, they are very different ways of building a project. In the Edge implementation, while you can use several services and tools available on the internet, you still need to have a physical device suited for the task. This as you will better see later implies some cost that might not be for everyone; on the other hand, keeping the computation closer to the edge allows to manipulate and change the data before sending it through the internet connection. The Cloud implementation instead has no need for you to prepare a group of devices since all of our project logic is uploaded to a virtual machine hosted

by some service. This lets you avoid the sunk cost of buying the boards but brings more expenses on the hosting. Moreover, having to upload each image in order to perform the prediction takes a considerable amount of time and bandwidth.

6.2.1 Execution Time

As the first parameter for our evaluation let's take a look at the execution time for each implementation. For the Edge Implementation, the Total Execution Time is the time needed for the acquisition and detection of gestures on the edge device, plus the time elapsed for the gestures to be sent via API to the DynamoDB and finally the time needed to store those gestures on the database.



Figure 6.1. Total Execution Time for Edge-Based System

For the recording, we have set up the script to make it record for ten seconds, after which it will start sending frame by frame to the lambda function in charge of prediction. The effective number of frames sent for prediction will depend on the webcam used for the video recording and by the video itself. This is caused by the fact that the frames are retrieved from the video product, once every ten frames (configured statically), which means that a webcam able to record at a higher frame rate will produce more images in the ten second span. We understand that this effect might not be desired, which leaves room for improvement in the future of our project. With this in mind in a sample execution of the Edge System, we have successfully predicted gestures from 11 different images with the following statistics.

| Date | Timestamp | Description |
|-------------------------------|---------------|---|
| 2021-11-19T10:55:41.737+01:00 | 1637315741737 | Fri, 19 Nov 2021 09:55:41 +0000 - START |
| 2021-11-19T10:55:52.007+01:00 | 1637315752007 | Fri, 19 Nov 2021 09:55:52 +0000 - FIRST FRAME SENT |
| 2021-11-19T10:55:53.567+01:00 | 1637315753567 | Fri, 19 Nov 2021 09:55:53 +0000 - LAST FRAME SENT |
| 2021-11-19T10:55:52.006+01:00 | 1637315757700 | Fri, 19 Nov 2021 09:55:52 +0000 - PREDICTION ON FIRST FRAME |
| 2021-11-19T10:56:45.343+01:00 | 1637315805343 | Fri, 19 Nov 2021 09:56:45 +0000 - PREDICTION ON LAST FRAME |
| 2021-11-19T10:55:57.702+01:00 | 1637315758026 | Fri, 19 Nov 2021 09:55:57 +0000 - FIRST PUT ON DYNAMO |
| 2021-11-19T10:56:45.418+01:00 | 1637315805418 | Fri, 19 Nov 2021 09:56:45 +0000 - LAST PUT ON DYNAMO |

Figure 6.2. Execution example of Edge-Based System

10 seconds and 270 milliseconds time between starting point and last frame 1 second and 560 milliseconds between getting first frame and last frame 5 seconds and 693 milliseconds between first frame and first prediction 47 seconds and 643 milliseconds between first prediction and last prediction 326 milliseconds between first prediction and first put table in DynamoDB 47 seconds and 392 milliseconds between first put in DynamoDB and last put

So these are the results of execution for a sample test for the Edge implementation, as you can see, the operation that requires time the most is the gesture prediction made from the model starting from a single frame, just as we expected. When we talk about Cloud implementation instead, things are similar but with some important differences. In fact, in the Total Execution Time for the Cloud System, it is still present a step for image acquisition, but the detection is not performed on the device anymore, instead, we send the whole image via API call in step B' to predict the gesture in the Lambda function in step C'. Finally, we compute the time for storing said gesture in our Database. Just as before, the local Python program will record for ten seconds straight before retrieving the images, then it will start uploading.



Figure 6.3. Total Execution Time for Cloud-Based System

With the completed execution we have retrieved the following numbers regarding the system. If you notice, the images were uploaded both in S3 and in DynamoDB in a seemingly random manner. We decided to order them by the time of the creation of the Database item since that is the final product of our function.

| Date of upload on S3 Bucket | Timestamp of upload on S3 | Date of Put on DynamoDB | Timestamp of Put on DynamoDB | Frame |
|-----------------------------|---------------------------|---------------------------|------------------------------|--------------------|
| 2021-11-03T09:53:12+00:00 | 1635933192273 | 2021-11-03T09:55:03+00:00 | 1635933303378 | images/frame10.jpg |
| 2021-11-03T09:53:15+00:00 | 1635933195501 | 2021-11-03T09:55:01+00:00 | 1635933301659 | images/frame50.jpg |
| 2021-11-03T09:53:15+00:00 | 1635933195319 | 2021-11-03T09:54:56+00:00 | 1635933296173 | images/frame70.jpg |
| 2021-11-03T09:53:14+00:00 | 1635933194373 | 2021-11-03T09:54:49+00:00 | 1635933289264 | images/frame40.jpg |
| 2021-11-03T09:53:15+00:00 | 1635933195335 | 2021-11-03T09:54:46+00:00 | 1635933286448 | images/frame20.jpg |
| 2021-11-03T09:53:15+00:00 | 1635933195488 | 2021-11-03T09:54:37+00:00 | 1635933277252 | images/frame60.jpg |
| 2021-11-03T09:53:14+00:00 | 1635933194775 | 2021-11-03T09:54:33+00:00 | 1635933273831 | images/frame30.jpg |
| 2021-11-03T09:53:15+00:00 | 1635933195438 | 2021-11-03T09:54:30+00:00 | 1635933270826 | images/frame0.jpg |
| | | | | |

Figure 6.4. Execution example of Cloud-Based System

1 minute 47 seconds and 940 from first upload on S3 and last put on DynamoDB 32 seconds and 552 from first to last put on DynamoDB 3 seconds and 228 from first to last upload on S3

6.3 Cost Analysis

We understand that in every project one important aspect for the implementation is the cost sustained in each part of the system. This means that a cost analysis is crucial when deciding if the system can be employed, to have a better understanding of where and how the costs are distributed and how to achieve equal or even better results without influencing negatively the total expenses foreseen for a given period of time. For this reason, we decided to make use of the Pricing Calculator provided by Amazon Web Services to estimate the costs of several case studies concerning different situations that require more or less the same services but in significantly different quantities. We have prepared 3 different situations that will be briefly elaborated on here.

6.3.1 A Private Smart-Store

In this first study, we show an estimation of costs that would be sustained by an entrepreneur that, caring deeply for the inclusion of all her customers, decided to implement our project in her smart clothing store. In this case, being her store relatively small and the percentage of her hearing-impaired customer probably on a single digit, she does not need a lot of edge devices in order to satisfyingly implement our project. We think that even a single device should be enough. This obviously means that the usage of each service will be limited, and possibly even covered by the free tier offered by AWS. Even if this wasn't the case, considering that she does not need to train her own model, she doesn't need to have cloud infrastructure and considering that the Database usage will be pretty low, the total costs that she would have to pay in a 1-year usage of our project are small enough to be affordable by a single private individual. The only upfront cost not considered in the pricing calculator is the price that needs to be paid to acquire a camera-equipped device. This is a una tantum cost that we approximated to $30 \notin$.

| Store Costs Edit 🗹 | | | |
|--------------------------|--------------------------|-----------------------------------|--|
| Estimate summary Info | | | |
| Upfront cost 0.00 USD | Monthly cost 2.53 USD | Total 12 months cost 30.36 USD | |

Figure 6.5. Costs Estimation for a Smart-Store

6.3.2 A National Hotel Chain

In our second case study we consider a national hotel chain in which most workers, scattered in different structures across Italy, unfortunately, have no knowledge of the ISL and, since training them would be very costly and time-consuming, decided to try and use the product we provide. We imagine a case where deaf visitors would need to check-in or communicate to the front desk in order to have their needs met. Cause of the nature of the hotel chain, a single device would not be enough anymore and more extensive use of the described services is expected. For this reason, we imagined a case where 10 Greengrass devices are used in the hotel buildings where more customers are welcomed and thus there is a greater need for faster detection and recognition of gestures. While in less "popular" tourist spots a Cloud Implementation would work just fine. Both the Cloud System and the greater number of smart devices will influence the cost considerably, but not having to re-train the model lower the expenses considerably.

| Hotel costs Edit 🗹 | | | | | |
|--------------------------|---------------------------|------------------------------------|--|--|--|
| Estimate summary Info | | | | | |
| Upfront cost 0.00 USD | Monthly cost 16.28 USD | Total 12 months cost 195.36 USD | | | |

Figure 6.6. Costs Estimation for a National Hotel Chain

6.3.3 Smart Hospital

Finally, we can locate a comprehensive implementation of all available services in a hospital, with the whole service being pretty substantial. As seen in the figures below, developing a full model and keeping it up to date can be costly, but it allows for higher precision and accuracy in the model. With the approval of the user's privacy, it is therefore feasible to track the latter's movements in order to diversify the information. Because a significant number of devices are necessary for efficient operation, the AWS CloudFormation service is a critical resource for deploying the complete service across the hospital network.

Given the massive quantity of predictions to store, a comprehensive review of the expenses reveals that Sagemaker, GroundTruth, and DyanmoDB are the most costly

services monthly.

| Services | Description | Monthly |
|------------------------------------|--|-----------------------------------|
| Amazon Elastic Container Registry | DT Inbound: Internet (1 GB per month), DT Outbound: Amazon CloudFront (1 GB per month), Amount of data stored (964 GB per month) | 96.40 USD |
| AWS IoT Core | Number of devices (MQTT) (100), Average size of each message (1 KB), Average size of each record (1 KB), Average size of each record (1 KB), Average number of actions executed per rule (1), Average size of each message (1 KB), Number of messages for a device (20) | 0.35 USD |
| AWS CloudFormation | Number of third-party resources managed (0), Average duration per operation (30 seconds), Total number of operations per resource (0 per day) | 0.00 USD |
| AWS CodePipeline | Number of active pipelines used per account per month (3) | 2.00 USD |
| Amazon DynamoDB | Average item size (all attributes) (87 Byte), Write reserved capacity term (1 year), Read reserved capacity term (1 year), Data storage size (1 GB) | 29.93 USD Upfront : 203.40 USD |
| AWS Lambda | Lambda Function - Without Free Tier Architecture (x86), Architecture (x86) | 0.00 USD |
| AWS IoT Greengrass | Number of greengrass core devices (100), Activity Period in minutes per month (6000) | 18.24 USD |
| Amazon SageMaker Ground Truth | Dataset object type (Other (e.g., Images, Video frames, Text documents)), Number of dataset objects (1200 per month), Number of workers per dataset object (0) | 96.00 USD |
| Amazon SageMaker | Instance name (ml.p3.8xlarge), Number of data scientist(s) (1), Number of Studio Notebook instances per data scientist (1), Studio Notebook hour(s) per day (1), Studio Notebook day(s) per month (1) | 15.86 USD |
| Amazon Simple Storage Service (S3) | S3 Standard storage (2 GB per month) | 0.13 USD |

(a) Details of Costs for each service

| aws pricing calculator | | | |
|---|----------------------------|-----------------------------------|-------------|
| AWS Pricing Calculator > Hospital Costs | tal costs | | Add service |
| Estimate summary Info | | | |
| Upfront cost 203.40 USD | Monthly cost 258.91 USD | Total 12 months cost 3,310.32 USD | |

(b) Costs Estimation for a Smart-Hospital

Figure 6.7. Cost Estimation and Details
Chapter 7

Conclusions and Future Works

The main purpose of the thesis is to demonstrate, starting from the design, implementation, and Deployment of an MLOps pipeline from the Cloud to the Edge environment can be a viable alternative to the advancement of new technologies and devices. We demonstrated various implementation options and also gave the code we used to encourage anyone with little knowledge of code and scripts to attempt to create a system similar to ours. On the other hand, we also emphasized the key distinctions between our two macro-sections of work. As IoT becomes more pervasive, edge computing will do the same. The ability to analyze data closer to the source will minimize latency, reduce the load on the internet, improve privacy and security, and lower data management costs. However, even when utilizing appropriate services and tools, its configuration is more complicated, especially when a large number of devices must be added to the group. We attempted to mitigate these issues by developing an AWS CloudFormation Stack that just requires the Core Certificate Arn of the device to be added to the system. In terms of cost, Edge Implementation necessitates the acquisition of all of the various smart devices, which might be costly depending on the number of them. The Cloud Implementation is simpler to set up and does not require the usage of a smart board for execution, but it comes at the cost of a "slower" forecast and higher costs due to the cloud service utilized to host our function. Furthermore, although the source code for Edge devices may be adjusted without much work by producing a new zip file including the Lambda, updating or changing the Cloud system's single function is not as straightforward. Thanks to Docker CLI, the Cloud Function operates as an image container; this implies that each change, debugging, or update will need creating, building, and pushing a new docker image for the Lambda service to retrieve. In conclusion, we can observe that The Cloud will continue to play a key role in accumulating crucial data and executing analytics on it to extract insights that can be transmitted back to edge devices, therefore Edge and cloud computing together can enable you better manage and analyze your data, boosting the value of your IoT initiatives dramatically.

7.1 Future works

Further development might be directed toward developing a model that identifies not only static movements of sign language, such as the alphabet but the entire vocabulary, requiring a more comprehensive study of the entire movement of the arms-producing gesture. Given the high number of data to analyze, of course, we will get a reliable model, but relying on the services of AWS will include a high creation time, and as a result, the costs will also be high. Finally, for future deployments, we have planned to include an LCD and a speaker in the embedded system. The end-user will be able to view the system's reaction in real-time and interact with it directly by integrating the two devices. We built the entire project on a virtual Linux system with a camera, but in the future, we'd like to utilize an AIoT-compatible board. The ESP-EYE is a development board for image recognition and audio processing that may be used in several IoT applications. It has a 2-megapixel camera and a microphone, as well as an ESP32 CPU. The ESP-EYE has enough storage with an 8 Mbyte PSRAM and a 4 Mbyte flash. It contains a Micro-USB port for debugging and Wi-Fi for picture transmission, as well as AWS-IoT and other AWS services connectivity out of the box.



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